

(FILE 'HOME' ENTERED AT 11:12:36 ON 20 MAY 2003)

FILE 'USPAT2, EUROPATFULL, JAPIO, INPADOC, INSPEC, NLDB, PATOSEP,
PATOSWO' ENTERED AT 11:13:01 ON 20 MAY 2003

L1 13 S (OPERATING(W) SYSTEM) (S) (EMULAT? (2A) OBJECT)
L2 5 S (EMULATION(W) OBJECT)
L3 0 S L2 AND OPERATING(W) SYSTEM
L4 143 S (EMULAT?(S) OBJECT) (P) (OPERATING(W) SYSTEM)
L5 43 S (EMULAT?(S) OBJECT) (S) (DIRECT? OR LINK? OR INTERFAC?) (S) (OPERA
L6 68 S (EMULAT?(3W) OBJECT)
L7 46 S (EMULAT?(2W) OBJECT)
L8 16 S (EMULAT?(3W) OBJECT) (P) (OPERATING(W) SYSTEM)

=>

Trying 3106016892...Open

```
Welcome to STN International! Enter x:x  
LOGINID:ssspta2700akr  
PASSWORD:  
TERMINAL (ENTER 1, 2, 3, OR ?):2
```

Enter NEWS followed by the item number or name to see news on that specific topic.

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FILE 'HOME' ENTERED AT 09:59:46 ON 06 MAR 2000

=> file europatfull inspec japiro nlldb patosep patoswo promt uspatfull

COST IN U.S. DOLLARS	SINCE FILE ENTRY	TOTAL SESSION
FULL ESTIMATED COST	0.45	0.45

FILE 'EUROPATFULL' ENTERED AT 10:01:16 ON 06 MAR 2000
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FILE 'USPATFULL' ENTERED AT 10:01:16 ON 06 MAR 2000
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=> s (pos or (point(w)of(w)sale) or register)

3 FILES SEARCHED...
L1 384825 (POS OR (POINT(W) OF(W) SALE) OR REGISTER)

=> s l1 and (emulat and (application(3w)develop?))

AND IS NOT A RECOGNIZED COMMAND

The previous command name entered was not recognized by the system.
For a list of commands available to you in the current file, enter
"HELP COMMANDS" at an arrow prompt (>).

=> s l1 and emulat? and (application(3w)develop?)

2 FILES SEARCHED...
7 FILES SEARCHED...
L2 273 L1 AND EMULAT? AND (APPLICATION(3W) DEVELOP?)

=> s l1 and (emulat?(s)(application(3w)develop?))

2 FILES SEARCHED...
PROXIMITY OPERATOR LEVEL NOT CONSISTENT WITH
FIELD CODE - 'AND' OPERATOR ASSUMED 'EMULAT?(S) (APPLICATION'
7 FILES SEARCHED...
L3 43 L1 AND (EMULAT?(S) (APPLICATION(3W) DEVELOP?))

=> s l3 and (emulat?(2w)module)

L4 1 L3 AND (EMULAT?(2W) MODULE)

=> d

L4 ANSWER 1 OF 1 USPATFULL
AN 1998:59535 USPATFULL
TI Computer emulator
IN Ogata, Hideaki, Nagano-Ken, Japan
Tanimoto, Akihito, Nagano-Ken, Japan
Nakaoka, Yasushi, Nagano-Ken, Japan
Kojima, Masanori, Nagano-Ken, Japan
Akahori, Yutaka, Nagano-Ken, Japan
PA Seiko Epson Corporation, Tokyo, Japan (non-U.S. corporation)
PI US 5758124 19980526
AI US 1995-559223 19951117 (8)
PRAI JP 1994-309813 19941118
DT Utility
LN.CNT 883

INCL INCLM: 395/500.000
INCLS: 395/527.000; 395/421.030; 364/DIG.001; 364/232.300; 364/DIG.002;
364/927.810; 364/955.500
NCL NCLM: 395/500.480
NCLS: 395/527.000; 711/213.000
IC [6]
ICM: G06F009-455
EXF 395/500; 395/375; 395/750; 395/800; 395/416; 395/527; 395/421.03;
364/200MSFile; 364/900MSFile; 364/927.81

=> d kwic

L4 ANSWER 1 OF 1 USPATFULL
AB . . . The emulator emulates routines that are called via a jump table
such as the BIOS. Control is transferred to an **emulation module** not by directly trapping the procedure to call the BIOS but by placing a privileged instruction (a halt instruction, for . . . trap through the execution of the privileged instruction. An identifier is placed after the halt instruction and a needed BIOS **emulation module** is called by a dispatcher using this identifier.
Therefore, normal operation can be obtained even if there is a resident.

SUMM A conventional virtual computer **emulator** of this type which makes **application programs developed** for a target machine executable on an executing machine by individually **emulating** OS function calls, BIOS function calls, I/O instructions and interrupt tables of the target machine has been known as disclosed. . .
DETD . . . also used when one execution module calls another module and when modules that are to communicate with each other mutually **register** the other's entry point EP for direct calling. For example, when one execution module calls another execution module, the service. . .
DETD Subsequent to the routine to **register** interrupts, it is determined whether the calling module is a module which has entry point EP for direct calling in. . .
DETD . . . module for emulation of the BIOS will be explained below. FIG. 14 is a flow chart showing the routine to **register** a BIOS emulation function. Prior to the onset of this routine, the BIOS for a PC-9800 is allocated to the. . .
DETD . . . interrupt routine for said interrupt and the BIOS is called. The contents of jump table JT corresponding to the BIOS **emulator module** currently being established, i.e., the go-to address, are then obtained and saved in a prescribed area. This address is saved. . . request is made using the same software interrupt, the process to be executed varies depending on the value in the **register**, and when a routine described below in which BIOS emulation is not performed is requested, control may be transferred to. . .
DETD With regard to various execution modules including BIOS **emulation modules**, **module name** (characters) TM and call address A at the minimum need to be registered in dispatcher table DT at the. . .
DETD . . . into an address in which a HLT instruction and an identifier are embedded in the initialization process when this BIOS **emulation module** was registered (see FIG. 14), in actuality, the HLT instruction, not the BIOS program, is executed (E2).
DETD . . . following the HLT instruction, i.e., the identifier. After obtaining the identifier, kernel KR requests dispatcher DP to call the BIOS **emulation module** using said identifier (E6). Receiving this request, dispatcher DP refers to dispatcher table DT registered and calls the BIOS routine prepared as an **emulation**

module (E7).

DETD If the BIOS routine prepared as an **emulation module** is a routine to access the floppy disk device, for example, it controls compound I/O ports 54 and floppy disk. . . as DOS/V hardware. FIG.

17 shows an example in which data is read from floppy disk device 82. The BIOS **emulation module** reads 256 bytes of data from floppy disk device 82 and saves it in buffer area FBF (F1 and F2). The data read into buffer area FBF is transferred to disk buffer FB of the system by the BIOS **emulation module**.

DETD After these sequences, processing by the BIOS **emulation module** is completed and control returns to the next instruction after the BIOS call of application program APP (E8). The return. . .

DETD . . . instruction (a HLT instruction in the embodiment) is executed in the called routine, whereupon control is transferred to the BIOS **emulation module**. Therefore, the BIOS **emulation module** can be activated through reliable detection of the call not only where the BIOS is called via a software interrupt. . . called by obtaining its entry point through referring to the jump table. Moreover, both the resident program and the BIOS **emulation module** can be normally operated even where there is an incorporated resident program of the type that operates after taking over. . .

DETD . . . large program to emulate a large number of functions may be efficiently developed. Moreover, since execution modules, including a BIOS **emulation module**, are modularized in a manner similar to the functioning of hardware, if application program APP is one that directly accesses. . .

DETD Subsequently, when the BIOS is called by application program APP, kernel KR activates immediately and transfers control to the BIOS **emulation module** via dispatcher DP. Therefore, the BIOS call is reliably detected in the second embodiment as well as in the first. . .

=> d ab

L4 ANSWER 1 OF 1 USPATFULL

AB What is disclosed is an emulator that emulates on an execution machine the operation of a target machine. The emulator emulates routines that are called via a jump table such as the BIOS. Control is transferred to an **emulation module** not by directly trapping the procedure to call the BIOS but by placing a privileged instruction (a halt instruction, for example) in the area called and by causing a trap through the execution of the privileged instruction. An identifier is placed after the halt instruction and a needed BIOS **emulation module** is called by a dispatcher using this identifier. Therefore, normal operation can be obtained even if there is a resident program which rewrites the jump table.

=> d

L4 ANSWER 1 OF 1 USPATFULL
AN 1998:59535 USPATFULL
TI Computer emulator
IN Ogata, Hideaki, Nagano-Ken, Japan
Tanimoto, Akihito, Nagano-Ken, Japan
Nakaoka, Yasushi, Nagano-Ken, Japan
Kojima, Masanori, Nagano-Ken, Japan
Akahori, Yutaka, Nagano-Ken, Japan

PA Seiko Epson Corporation, Tokyo, Japan (non-U.S. corporation)
PI US 5758124 80526
AI US 1995-559223 19951117 (8)
EIAI JP 1994-309813 19941118
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INCL INCLM: 395/500.000
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364/927.810; 364/955.500
NCL NCLM: 395/500.480
NCLS: 395/527.000; 711/213.000
IC [6]
ICM: G06F009-455
EXF 395/500; 395/375; 395/750; 395/800; 395/416; 395/527; 395/421.03;
364/200MSFile; 364/900MSFile; 364/927.81

=> d hist

(FILE 'HOME' ENTERED AT 09:59:46 ON 06 MAR 2000)

FILE 'EUROPATFULL, INSPEC, JAPIO, NLDB, PATOSEP, PATOSWO, PROMT,
USPATFULL' ENTERED AT 10:01:16 ON 06 MAR 2000

L1 384825 S (POS OR (POINT(W)OF(W)SALE) OR REGISTER)
L2 273 S L1 AND EMULAT? AND (APPLICATION(3W)DEVELOP?)
L3 43 S L1 AND (EMULAT?(S) (APPLICATION(3W)DEVELOP?))
L4 1 S L3 AND (EMULAT?(2W)MODULE)

=> s l3 and execut?

L5 37 L3 AND EXECUT?

=> s l3 and (application(s)execut?)

PROXIMITY OPERATOR LEVEL NOT CONSISTENT WITH
FIELD CODE - 'AND' OPERATOR ASSUMED 'PPLICATION(S)EXECUT?'
L6 32 L3 AND (APPLICATION(S) EXECUT?)

=> d 1-10

L6 ANSWER 1 OF 32 EUROPATFULL COPYRIGHT 2000 WILA
PATENT APPLICATION - PATENTANMELDUNG - DEMANDE DE BREVET

AN 961193 EUROPATEFULL ED 19991212 EW 199948 FS OS
TIEN Secure computing device.
TIDE Sichere Rechnervorrichtung.
TIFR Dispositif ordinateur securise.
IN Laczko Sr., Frank L., 301 S. Jupiter, P.O. Box 23, Allen, Collin
County,
Texas, US
PA Texas Instruments Incorporated, 7839 Churchill Way, Dallas, Texas
75251,
US
SO Wila-EPZ-1999-H48-T2a
DS R AT; R BE; R CH; R CY; R DE; R DK; R ES; R FI; R FR; R GB; R GR; R IE;
R IT; R LI; R LU; R MC; R NL; R PT; R SE; R AL; R LT; R LV; R MK; R RO;
R SI
PIT EPA2 EUROPÄISCHE PATENTANMELDUNG
PI EP 961193 A2 19991201
OD 19991201
AI EP 1999-201705 19990528
PRAI US 1998-87229 19980529

US 1998-871 19980529
US 1998-872 19980529
US 1998-87230 19980529
IC ICM G06F001-00
ICS G06F012-14

L6 ANSWER 2 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

PATENT APPLICATION - PATENTANMELDUNG - DEMANDE DE BREVET

AN 786722 EUROPATFULL ED 19970810 EW 199731 FS OS
TIEN A method and system for improving emulation performance.
TIDE Verfahren und Anordnung zur Leistungsverbesserung von Emulation.
TIFR Procede et systeme pour ameliorer la performance d'emulation.
IN Kahle, James A., 5312 Tortuga Trail, Austin, Texas 78731, US;
Mallick, Soummya, 13032 Partridge Bend Drive, Austin, Texas 78729, US
PA INTERNATIONAL BUSINESS MACHINES CORPORATION, Armonk, NY 10504, US
SO Wila-EPZ-1997-H31-T2a
DS R DE; R FR; R GB
PIT EPA1 EUROPÄISCHE PATENTANMELDUNG
PI EP 786722 A1 19970730
OD 19970730
AI EP 1996-309517 19961227
PRAI US 1996-581793 19960125
IC ICM G06F009-318

L6 ANSWER 3 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

PATENT APPLICATION - PATENTANMELDUNG - DEMANDE DE BREVET

AN 712077 EUROPATFULL UP 19970408 EW 199620 FS OS STA R
TIEN Microcontroller with provisions for emulation.
TIDE Mikrokontroller mit Einrichtung zur Emulation.
TIFR Microcontroleur avec dispositions pour l'emulation.
IN Iles, Alexander L., 6912 Chinook Drive, Austin, Texas 78736, US;
Jelemensky, Joseph, 4606 Palisade Drive, Austin, Texas 78731, US;
Yishay, Oded, 7790 Lekewood Drive, Austin, Texas 78750, US
PA MOTOROLA, INC., 1303 East Algonquin Road, Schaumburg, IL 60196, US
SO Wila-EPZ-1996-H20-T2a
DS R DE; R FR; R GB
PIT EPA1 EUROPÄISCHE PATENTANMELDUNG
PI EP 712077 A1 19960515
OD 19960515
AI EP 1995-116864 19951026
PRAI US 1994-333658 19941103
IC ICM G06F011-00

L6 ANSWER 4 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

PATENT APPLICATION - PATENTANMELDUNG - DEMANDE DE BREVET

AN 685793 EUROPATFULL ED 19991107 EW 199549 FS OS STA B
TIEN Emulation device, system and method with distributed control of test
interfaces in clock domains.
TIDE Vorrichtung, System und Verfahren zur Emulation mit dezentraler
Steuerung im Taktbereich-Pruefungsschnittsteller.
TIFR Dispositif, systeme et procede d'emulation avec commande decentralisee
d'interface de test.
IN Swoboda, Gary L., 4435 Balboa, Sugar Land, TX 77479, US
PA TEXAS INSTRUMENTS INCORPORATED, 13500 North Central Expressway, Dallas
Texas 75265, US
SO Wila-EPZ-1995-H49-T2a
DS R DE; R FR; R GB; R IT; R NL
PIT EPA2 EUROPÄISCHE PATENTANMELDUNG
PI EP 685793 A2 19951206

OD 19951206
AI EP 1995-30 19950309
PRAI US 1994-208543 19940309
US 1994-209127 19940309
US 1994-208469 19940309
IC ICM G06F011-26

L6 ANSWER 5 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

GRANTED PATENT - ERTEILTES PATENT - BREVET DELIVRE

AN 469507 EUROPATFULL ED 19970307 EW 199637 FS PS
TIEN Integrated circuit comprising a standard cell, an application cell and
a test cell.
TIDE Integrierte Schaltung mit einer Standardzelle, einer Anwendungszelle
und einer Pruefzelle.
TIFR Circuit integre comprenant une cellule standard, une cellule
d'application et une cellule de test.
IN Dartois, Luc, 98, avenue Paul Denis Huet, F-78955 Carrieres sous
Poissy,
FR;
Dulongpont, Jacques, 6, rue Albert Thomas, F-95300 Pontoise, FR;
Reusens, Peter, Warande 121, B-9270 Laarne, BE
PA ALCATEL MOBILE COMMUNICATION FRANCE, 15, rue de la Baume, 75008 Paris,
FR
SO Wila-EPS-1996-H37-T2
DS R AT; R BE; R CH; R DE; R DK; R ES; R FR; R GB; R GR; R IT; R LI; R LU;
R NL; R SE
PIT EPB1 EUROPÄISCHE PATENTSCHRIFT
PI EP 469507 B1 19960911
OD 19920205
AI EP 1991-112697 19910729
PRAI FR 1990-9978 19900803
REP EP 315475 A EP 358376 A
US 4698588 A
REN COMPUTER DESIGN, vol. 29, no. 17, 1 septembre 1990, Littleton,
Massachusetts, US, pages 94-112; J. GABAY: "How much can
Design-for-test
reduce the need for testing?" IBM TECHNICAL DISCLOSURE BULLETIN, vol.
25, no. 2, juillet 1982, NEW YORK, US, page 709; E.F. HAHN et al.:
"VLSI
testing by on-chip error detection"
IC ICM G06F011-26
ICS G01R031-28

L6 ANSWER 6 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

GRANTED PATENT - ERTEILTES PATENT - BREVET DELIVRE

AN 437550 EUROPATFULL ED 19971221 EW 199750 FS PS
TIEN INFORMATION PROCESSING SYSTEM EMULATION APPARATUS AND METHOD.
TIDE VERFAHREN UND VORRICHTUNG ZUR EMULATION EINES
INFORMATIONSSYSTEMS.
TIFR METHODE ET APPAREIL D'EMULATION POUR UN SYSTEME DE TRAITEMENT DE
L'INFORMATION.
IN MORSS, Stephen, 1 Fairmount Avenue, Somerville, MA 02144, US;
DREYFUS, Boris, 77 Bow Street, Lexington, MA 02173, US
PA WANG LABORATORIES, INC., 600 Technology Park Drive, Billerica, MA
01821,
US
SO Wila-EPS-1997-H50-T2
DS R BE; R DE; R FR; R GB; R NL
PIT EPB1 EUROPÄISCHE PATENTSCHRIFT (Internationale Anmeldung)

PI	EP 437550	B1 19971210
OD		19910724
AI	EP 1990-905836	19900328
PRAI	US 1989-367297	19890615
RLI	WO 90-US1642	900328 INTAKZ
	WO 9016027	901227 INTPNR
REP	EP 168034 A	EP 205949 A
	EP 260568 A	US 3938101 A
	US 4875186 A	
IC	ICM G06F013-10	
	ICS G06F009-44	

L6 ANSWER 7 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

GRANTED PATENT - ERTEILTES PATENT - BREVET DELIVRE

AN	372834 EUROPATFULL ED 19970108 EW 199625 FS PS
TIEN	Translation technique.
TIDE	Uebersetzungsverfahren.
TIFR	Methode de traduction.
IN	Goettelmann, John Charles, 1846 Southeast Drive, Point Pleasant New Jersey 08742, US; Hiller, Ronald George, 1 Crawford Place, Old Bridge New Jersey 08857, US; Krantzler, Irvan Jay, 17 Alameda Court, Eatontown New Jersey 07724, US; Macey, Christopher James, 54 Elm Place, Red Bank New Jersey 07701, US; Tuomenoksa, Mark Logan, 20 Frances Street, Shrewsbury New Jersey 07702, US
PA	AT&T Corp., 32 Avenue of the Americas, New York, NY 10013-2412, US
SO	Willa-EPS-1996-H25-T2
DS	R DE; R FR; R GB; R IT
PIT	EPB1 EUROPÄISCHE PATENTSCHRIFT
PI	EP 372834 B1 19960619
OD	19900613
AI	EP 1989-312500 19891130
PRAI	US 1988-280767 19881206
REP	EP 168034 A
REN	SIGPLAN NOTICES vol. 22, no. 7, July 1987, YORKTON HEIGHTS N.Y. pages 1 - 13; C. MAY: 'Mimic: A fast system/370 simulator'
IC	ICM G06F009-455
	ICS G06F009-45

L6 ANSWER 8 OF 32 PROMT COPYRIGHT 2000 IAC

ACCESSION NUMBER:	97:253265 PROMT
TITLE:	Multimedia still drives the game
AUTHOR(S):	Ohr, Stephan
SOURCE:	Electronic Engineering Times, (5 May 1997) pp. 83. ISSN: 0192-1541.
LANGUAGE:	English
WORD COUNT:	3470

FULL TEXT IS AVAILABLE IN THE ALL FORMAT

L6	ANSWER 9 OF 32 USPATFULL
AN	2000:25940 USPATFULL
TI	Processor condition sensing circuits, systems and methods
IN	Swoboda, Gary L., Sugar Land, TX, United States
	Ehlig, Peter N., Houston, TX, United States
PA	Texas Instruments Incorporated, Dallas, TX, United States (U.S. corporation)
PI	US 6032268 20000229
AI	US 1992-832661 19920204 (7)
RLI	Continuation of Ser. No. US 1989-388286, filed on 31 Jul 1989, now abandoned And a continuation-in-part of Ser. No. US 1987-93463, filed on

4 Sep 1987, now abandoned Ser. No. Ser. No. 1987-140055, filed on 31 Dec 1987, now patented, Pat. No. US 5109494 Ser. No. Ser. No. US 1987-140192, filed on 31 Dec 1987, now patented, Pat. No. US 5101498 Ser. No. Ser. No. US 1989-347968, filed on 4 May 1989, now abandoned Ser. No. Ser. No. US 1989-347969, filed on 4 May 1989, now abandoned Ser. No. Ser. No. US 1989-347605, filed on 4 May 1989, now abandoned Ser. No. Ser. No. US 1989-347596, filed on 4 May 1989, now patented, Pat. No. US 5072418 Ser. No. Ser. No. US 1989-347615, filed on 4 May 1989, now patented, Pat. No. US 5142677 Ser. No. Ser. No. US 1989-347966, filed on 4 May 1989, now patented, Pat. No. US 5155812 And Ser. No. US 1989-347967, filed on 4 May 1989, now abandoned

DT Utility

LN.CNT 3972

INCL INCLM: 714/030.000

INCLS: 714/034.000; 714/726.000

NCL NCLM: 714/030.000

NCLS: 714/034.000; 714/726.000

IC [7]

ICM: G01R031-3177

ICS: G01R031-3185

EXF 371/16.2; 371/19; 371/22.3; 371/22.5; 714/30; 714/34; 714/726

L6 ANSWER 10 OF 32 USPATFULL

AN 1999:143711 USPATFULL

TI Pin management of accelerator for interpretive environments

IN Adams, Phillip M., Salt Lake City, UT, United States

PA Novell, Inc., Provo, UT, United States (U.S. corporation)

PI US 5983310 19991109

AI US 1997-799192 19970213 (8)

DT Utility

LN.CNT 1414

INCL INCLM: 711/006.000

INCLS: 711/163.000; 711/167.000; 711/123.000; 709/102.000; 709/103.000;
709/301.000; 710/008.000

NCL NCLM: 711/006.000

NCLS: 711/163.000; 711/167.000; 711/123.000; 709/102.000; 709/103.000;
709/301.000; 710/008.000

IC [6]

ICM: G06F009-32

EXF 711/6; 711/163; 711/167; 711/125; 711/123; 711/123-5; 395/681; 395/672;
395/826; 395/712; 395/672-3; 709/102-4; 709/301; 710/6-8

=> d ab 1

L6 ANSWER 1 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

ABEN A secure computing system (100) stores a program, preferably the real time operating system (210), that is encrypted with a private key. A boot ROM (135) on the same integrated circuit as the data processor and inaccessible from outside includes an initialization program and a public key corresponding to the private key. On initialization the boot ROM decrypts at least a verification portion of the program. On verification normal operation is enabled. On non-verification, the system could be disabled, or that application program could be disabled.

A diagnostic program is stored at predetermined non-relocatable physical address in memory. The program is made non-relocatable using a special table look-aside buffer (137) having a fixed virtual address register (611) and a corresponding fixed physical address register (641). The secure computing system prevents unauthorized use of compressed video data stored in a first-in-first-out memory buffer by encrypting the compressed video data stream using at

least a part of the chip identity number as an encryption key (703).

The data is recalled from memory (705) and decrypted (706) as needed for video decompression. The debugger/emulator tool commonly employed in program development is protected by a private encryption key used to encrypt at least verification token for the program. Upon each initialization of the debugger/ emulator, the secure computer system decrypts the verification token employing public decryption key (805) to indicate whether the program is secure or non-secure. <image>

=> d ab 2

L6 ANSWER 2 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

ABEN A system and method for improving the performance of a processor that emulates a guest instruction where the guest instruction includes a first and second operand. The first operand is stored in a general purpose register, and the second operand is stored in a special-purpose register. The method and system provides a host instruction that performs an operation using the first operand and the second operand without moving the second operand from the special-purpose register into the general purpose register. This reduces the number of instructions in the semantic routines necessary to operate on immediate data from guest instructions and increases emulation performance. <image>

=> d ab 3

L6 ANSWER 3 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

ABEN An integrated circuit terminal of a data processing system (10) is used to communicate multiplexed signals with an external device. During a reset operation in which a reset signal is asserted, a desired internal clock signal is driven to the integrated circuit terminal such that an emulation system (52) may use the internal clock signal to synchronize an emulation operation. After the reset signal is negated, the

emulation system synthesizes the internal clock signal for use during emulation. External visibility of a write operation to a register which controls pertinent signal parameters is provided via other integrated circuit terminals when the data processor operates in an emulation mode.

The external visibility allows the development system to make similar changes to corresponding signal parameters therein. Therefore, the development system is able to accurately synchronize an emulation operation even when signal parameters are modified during operation. <image>

=> d ab 4

L6 ANSWER 4 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

ABEN An emulation device (11) distributes common control information (8801) to each of a plurality of clock domains (1213, 1215, 1217) into which the emulation device is partitioned, and also provides the clock domains with individualized clock control (8905, 8907, 8913). <image>

=> d kwic 4

L6 ANSWER 4 OF 32 EUROPATFULL COPYRIGHT 2000 WILA
DETDEN In addition to testing for functionality and for manufacturing defects,

application software development requires a similar level of simulation, observability and controllability in the system

or

sub-system design phase. The emulation phase of design should ensure that an IC (integrated circuit), or set of ICs, functions correctly in the end equipment. . .

The . . . simulation and continually increasing cost of CAD (computer aided design) tools. In the board design the side effects include decreased register visibility and control, complicated debug and simulation in design verification, loss of conventional emulation due to loss of physical access by packaging many circuits in one package, increased routing complexity on the board, increased costs of design tools, mixed-mode packaging, and design for producability. In application

development, some side effects are decreased visibility of states, high speed emulation difficulties, scaled time simulation, increased debugging complexity, and increased costs of emulators. Production side effects involve decreased visibility and control, complications in test vectors and models, increased test complexity, mixed-mode packaging, continually. . .

Among the objects of the present invention are to provide improved emulation, simulation and testability architectures and methods which provide visibility and control without physical probing or special test fixtures; to provide improved emulation, simulation and testability architectures and methods which are applicable to critical components of system designs to support test

and

integration of both hardware and software; to provide improved emulation, simulation and testability architectures and methods that are a viable alternative to high capital-cost test equipment and systems; to provide improved emulation, simulation and testability architectures and methods which integrate access to sophisticated operations in hardware emulation, fault emulation, simulation and built-in test; to provide improved emulation, simulation and testability architectures and methods which apply hardware and software visibility and control to reduce application development time and thus reduce the user manufacturer's time-to-market on new products; and to provide improved emulation, simulation and testability architectures and methods to leverage hierarchical partitioning and automatically generate reusable tests for related chips and systems. . .

The . . . the adapter of Figs. 49, 51, 52, 53, 56 and 57;

FIG. 59A is a compact diagram of shift register latches SRLs in a scan chain in Fig. 59;

FIG. 60 is a schematic diagram of a code state. . . of clock waveforms for operating the GSP chip of Fig. 80;

FIG. 83 is a schematic of a parallel register latch for use in the GSP chip of Fig. 80;

FIG. 84 is a schematic of a serial register latch for use in the GSP chip of Fig. 80;

FIG. 85 is a block diagram of a control. . .

Extended development system 1101 provides full-speed, in-circuit emulation for system design and for hardware and software debug on widely available personal computer systems. The development tools provide technological. . . to prototype. The development system elements provide ease of use and offer the designer the tools needed

to

significantly reduce application system development time and cost to put designs into production faster.

Device . . . configuration file, a GSP (graphic signal processor) configuration, a programmable array logic (PAL) file, an ASIC file and a GPL register file.

The . . . software and hardware with the target system. An important

emulation interface provides control and access to every memory location and register of the target chip and extend the device architecture as an attached processor.

The . . . before the target system is complete. To accomplish this, code is downloaded into the memory on the board 1043 and executed at full speed via the interface on an application board used in place of the incomplete target system. A suitable application board includes a DSP 11, 16K x 32 bits of full-speed (zero wait states) SRAM on a primary bus, two.

The . . . Fig. 47 and disclosed in coassigned application SN 057,078

(TI-12033) filed June 2, 1987 and incorporated herein by reference. Shift register latches (SRLs) designated "S" are distributed through the device 11 like a string of beads on a serial scan path.

Figure . . . TDO communicate with the system. TMS and TCK communicate with a tap controller 1151 which is connected to an instruction register 1153 and an instruction decoding circuit 1155.

Test access port (TAP) controller 1151 is in turn coupled to instruction register (IR) 1153 and a first multiplexer 1173. The instruction register can receive serial scan signals from the TDI line and output serially to MUX 1173. MUX 1173 is under

control of the TAP and can select the output signal from the instruction register or from another MUX 1171.

The instruction register also controls a bypass register (BR) 1167 and one or more boundary scan registers (BSR) 1161. The bypass register receives the TDI signal and outputs it to MUX 1171. MUX 1171 is under control of the instruction register 1153. Based on the instruction loaded into the instruction register, MUX 1171 outputs its input from the bypass register or its input from one or more BSRs, or internal device register scan. Each boundary scan register is controlled via the test access port and the instruction register.

The . . . or a test mode. During the normal mode, input data entering terminals of IC logic passes through the boundary scan register, into the IC logic and out to the normal output terminals without any change due to the BSR. During the . . . test mode, normal input data is interrupted, and test input data is captured, shifted, and updated within the boundary scan register. The boundary scan register includes two

memories, a first memory for receiving and shifting data from the TDI line and a second memory for . . .

Generally, . . . controller card 1141 through pin TDI and enters any one of a number of shift registers, including a boundary scan register 1161, a device identification register 1163 and design specific test data registers 1165. A bypass register 1167 is also provided. These shift registers or serial scan registers are selected via a MUX 1171 under the control. . . . output from MUX 1171 is fed to a MUX 1173 so that under control of tap controller 1151 the instruction register 1153 or MUX 1171 is selected by MUX 1173. JTAG clock TCK and MUX 1173 output are fed to flip. . . . Returning . . . has two scan paths. One of the scan paths is termed the MPSD data path which usually has numerous shift register

latches S SRL) serially interconnected like a string of beads throughout module. The second scan path is termed the MPSD control path which generally has fewer shift register latches and which selects which MPSD data paths are to be scanned. These scan paths

are described in above-cited U.S. . . . The . . . core domain 1213, system domain 1215 and analysis domain 1217 are shown in Figure 50 and interface through the shift register latches of Fig. 47 to all of the various parts of the chip.

Figure . . . chip of device 11. JTAG control 1201 interfaces with the pins via a serial boundary scan assembly including boundary scan register 1161 which allows all logic states at the actual pins of device 11 to be read or written. JTAG TAP controller 1151 and JTAG instruction register IR 1153 are provided on-chip. Test control 1205 and MPSD control 1203 are integrated into the circuitry. MPSD control 1203. . . .

Referring . . . as the following five distinct clocking domains in order to control domain data transfers with the scan clock (JCLK) and application execution with the functional clock (FCLK).

- 1) CPU core domain 1213
- 2) Analysis domain 1217
- 3) Peripherals, memory, . . .

There . . . data is scanned to and from the device 11 through internal scan paths that are selected through a JTAG instruction register 1153. A unique JTAG opcode for each path allows entry of and access to internal scan data.

Figure 54 shows a further diagrammatic respective of the registers of Figure 50 wherein JTAG instruction register IR 1153 is selected for scan between the terminals TDI and TDO. The IR 1153 is decoded in Fig. 50. . . . requested by the control card 1141 of Figure 45 via the serial line 1103. These shift registers are the bypass register 1167, the boundary scan register 1161, the message peripheral 1216 of Fig. 52, the emulation control register 1251 and a pair of MPSD scan paths 1252 in the various domains and modules in the domains.

C1 . . . when not scanning and a zero when scanning. C0 and CX are sourced from the emulation control block adapter 1203 register 1251. When host computer 1101 detects Ready to Scan for all unlocked domains for a designated device on the target. . . .

Connected . . . mode conditioned stop logic circuitry 1309S, 1309C and 1309A in the domains respectively. The modes are established by a mode register 1311 which is scanable in Figs. 54 and 57 to establish the type of stop and any other desired mode. . . .

Then . . . sent to the CPU domain 1213 to make it stop according to the stop mode established for it in mode register 1311 and mode conditioned stop circuitry 1309C. DONE circuitry 1363 detects

when

the stop is completed and signals back to. . . .

Fig. . . . an example of process steps by which the scan control 1149 including IR 1153, adapter 1203 including ECR (emulation control register) 1251, and host computer 1101 cooperate to enter and perform sequences of commands on-chip.

Next . . . to reach the state "Select-DR-Scan". This means that the scan controller is ready to accept scan into a DR (data register) identified just before as the ECR 1251 by the host to the IR 1153. Into ECR 1251 the host 1101. . . .

In Figure 59, serial scan bits enter the emulation control register ECR 1251 which is subdivided into a shift register LOCK 1351 for holding bits to lock and unlock domains, a first C0,CX control code shift register named CODA 1353, a second C0,CX control code shift register named CODB 1357, a shift register 1359 associated with event manager circuitry 1365, and a two-bit register JMODE 1360. These registers are

compactly illustrated in Fig. 59A. Thus, the .al scan enters on a scan line SIN. . . .
A code state machine 1381 controls a two input MUX 1383. MUX 1383 selects the C0,CX two-bit contents of shift register 1353 or 1357 and loads them into an enabled one of three flip flops 1393, 1395 and 1397. A lock control circuit 1401 operating under the control of lock shift register 1351 and code state machine 1381 sends lock signals to disable or enable each of the flip flops 1393, 1395.

. . . Test . . . the test codes on line 1421, thus overriding the code state machine feature. This option is selected by scanning JMODE register with "00" (both bits zero). Thus, the preferred embodiment is accommodates direct host control of the domains, wherein the latter. . . .

In . . . and CODB 1357 as directed by a code state machine 1381;
2) Program state machine 1381 operations via REV_T (Register Event) register 1359 to respond to stimuli including:
a) START from scan control 1149
b) DONE from CPU core 1213, . . . to JCLK (with a code 00 in both registers 1353 and 1357) and vice versa for each domain, via LOCK register 1351; and
4) Lock domains in their current state while operating with other domains.

The operation of code state machine 1381 is now further described.
When

the JTAG IR (Instruction Register 1153) is loaded with a scan path select command for path 1251, a line ECRSEL feeds a signal to state. . . . whereupon the state machine 1381 enters a lock state. This allows the registers 1351, 1353 and 1357, the event manager register 1359, and JMODE register 1360 to be changed without disturbing the MPSD codes and clocks supplied from flip flops 1393, 1395, 1397 and selection circuits 1371, 1373 and 1375 to the domains 1215, 1213 and 1217. Lock register LOCK 1351 holds bits which selectively cause the CPU, analysis and system domains 1213, 1217 and 1215 to be frozen. . . .

A NAND gate 1471 supplies a SET input of SRL 1451 in response to two inputs ECRSEL (emulation control register select) and START from Fig. 50. An AND gate 1473 supplies a RESET input of SRL 1451 in response to. . . .

Shift register 1359 includes scannable register -event bits REV_T3, REV_T2, REV_T1 and REV_T0. REV_T3 is a scanable bit inverted by an inverter 1483 to signal a NAND. . . . to CNTBRW, DONE and EMU1. Additional NAND gates for EMU0 and other signals are readily providable, as are further event register cells in shift register 1359.

The . . . MPSD control code currently applied to the domains when the emulation control path ECR 1251 is selected by the instruction register IR 1153 and a START pulse is generated. The code state machine 1381 exits the lock state upon a START. . . .

The . . . registers 1353 and 1357 selected by the code state machine

1381. When the code state machine 1381 points to a register CODA or CODB containing a different clock source for that state, the clock switch 1411, 1413 or 1415 corresponding to the unlocked domain selected by LOCK register 1351 and lock control 1401 locks the code of the old state by signaling NOT GCTD (Not Good Clock This).

. . . In Fig. 62, selecting circuit 1383 has two MUXes 1501 and 1503 for respectively selecting the C0,CX control code from register CODA or CODB in response to signal LSB from the code state machine

CODAO and C0, and in register CODB are C0 and CODBX. The selected code is held in a pair of SRLs 1507 for C0 and 1509.

In . . . OR gates 1531, 1533 and 1535 each having first inputs connected respectively to lines LOCKRQS, LOCKRQC and LOCKRQA from LOCK register 1351 of Fig. 59, and outputs connected respectively to lines LOCKS, LOCKA and LOCKC of Figs. 59 and 62. These . . . 1455 of Fig. 60. The AND gate 1543 has two inputs connected to SWINPROG

and

nclksel. In this way, LOCK register 1351 bits override any other signals when the bits call for locking the domain (test clock JCLK only). However, if register 1351 unlocks any one or more domains (calling for functional clock FCLK to each such domain), each such domain can. . .

In . . . and 1565. This block 1205 is enabled by a low active OR 1571 supplied from the two bits of JMODE register 1360 of Fig. 59. Code conversion logic block 1205 thus converts to MPSD code from any three-wire testability code scheme. . .

In . . . the operational mode of the device for the entire session. The operating mode is specified in a separate emulation mode register or module 1311 which is scan-loaded while the CPU core is halted. This advantageous mode feature involves mode driven stops..

The particular stop mode of the processor is determined by mode register 1311 of Fig. 57, as already discussed. The location, placement in any Particular register, and scanability of each of the bits of the stop mode is quite flexible. In another example,

the

particular stop. . . If the stop mode is generally not changed frequently in practice, then it can be put in a separate mode register 1311 to avoid unnecessary scan bits in the various domains. Otherwise, the various stop mode bits can be allocated to. . .

In . . . transferred to initiate a memory or I/O transaction, especially when the memory transfer is a single word. When the entire register file may be used to create a block transfer, multiple scan modules may be used.

Advantageously, . . . confers a level of concurrency beyond more JTAG boundary scan. Microprocessors, for one example, are a very valuable and complex application with access to the internal information very important. Since JTAG boundary scan involves a test port, this test port is. . . communication to specific chips one at a time or all together, concurrently. The preferred embodiment puts commands in emulation control register 1251 and loosely couples the communication so that the device 11 can run in real time when desired. In this. . . to the commands such as CODA and CODB

in

Fig. 59, in contrast to loading the JTAG IR 1153 and executing an operation by decode.

Thus, the bits which are scanned in are loaded into a 12 bit register 1707, 3 bit register 1709 and single bit registers 1711.1 through 1711.8 in this section of the analysis domain 1217.

The three bits in shift register 1709 make a one of eight selection by MUX 1713 and supply the selected line to a 12 bit down.

. counter 1715. A predetermined count is loaded into the J (jam) parallel input of counter 1715 from 12 bit shift register 1707. As signals on the line selected by MUX 1713 occur, the 12 bit down counter counts down until the number represented by the contents of shift register 1707 is exhausted, whereupon a borrow line 1717 goes active and is fed to selector 1703.1. The borrow line signal. . .

An . . . utility of the down counter 1715 (besides single-stepping) is as follows. Assume that the counter 1715 is set by scan

register 1707 . . . 200 and the MUX 1713 is set by register 1709 to select BPDA data address breakpoint. The particular data address is scan-entered in a register 1813 in Fig. 71. This configuration stops the processor after the specific scan-identified data address has been addressed 200 times. . . . In another filter example, the counter borrow line is selected by scan register 1711.1 and fed out of pin EMU0 to permit external logic to count events at a rate stepped down by. . . .

When external logic is used, its resolution is equal to the number set for the counter 1715 by register 1707. Full resolution is obtained by reading out the value in the 12 bit down counter, allowing determination of the. . . .

In . . . step 1737, a trace stack full condition is sensed. Then a step 1739 selects which conditions are relevant using shift register 1711 and logic 1703 of Fig. 69 for example. Of the conditions selected, a count is kept in step. . . .

In . . . bus 101A of Fig. 68A is connected to a digital comparator 1811. A reference value is scan-loaded into a further register 1813 in the analysis domain having most significant bits MSB and least

significant bits LSB. When a program address asserted on address bus 101A is identical to the contents of register 1813, then comparator 1811 produces an output indicative of a breakpoint address occurrence on line BPPA.

In . . . any address within a selected group of addresses such as the ramp; indicated by the most significant bits MSB of register 1813. In such case, a scanable mask register LSBEN is scan-loaded to disable the response of comparator 1811 to

the LSB bits of register 1813. Only the most significant bits are compared by comparator 1811 in this mask condition, thereby providing a

breakpoint on. . . .

Scanable register 1813 for breakpoint purposes requires no connection to data bus 111D. However, this register 1813 is advantageously reused for message passing access between the emulation/simulation/test host computer 1101 of Fig 45 and the data.

. of the target device. The message passing function is used when breakpoint sensing need not occur, and vice-versa, so that register 1813 feasibly performs different functions at different times.

In . . . address discontinuities in operation of program counter 93 of Fig. 68A in the CPU core domain. A scanable trace stack register section 1823 responds to control circuit 221 to push a program counter 93 address value onto the trace stack when. . . .

The state vector leading bits of the program counter trace stack 1821 resemble a shift register for stack purposes and the S/E9 end of the shift register is output to an OR gate 1825. OR gate 1825 is further connected to a program count shift out register PCSO 1827. The output of PCSO 1827 is fed back to a second input of OR gate 1825. When a first logic one is pushed from

the bottom of the stack 1821 into OR gate 1825, register 1827 indicates the output trace stack full TRFUL for analysis circuitry of Fig. 69. Subsequent push onto stack 1823 pushes out a subsequent zero from the stack into OR gate 1825. However, register 1827 continues to be loaded by OR-gate 1825 (by virtue of the feedback from PCSO to 1825) with a one. . . .

Figure . . . in the device 11. A serial scan path of Figs. 54 and

78 has serial data MSIN enter a shift register 1923 CMD/STATUS for entry of commands to operate the message passing circuitry 1216 and for scan out of status information. The serial path continues to a

further serial **register** 1925 designated 16 bit DATA
REGISTER whereupon the scan path exits on a line designated MSOUT. These shift registers correspond to serial/parallel interface 1881 of Figure 76. The function of shift **register** 1925 can be implemented by **register** 1813 in the analysis domain and reuse principles can generally minimize the chip real estate required for message passing.

The shift **register** 1925 is connected to the output of a MUX 1931 which selects one of three paths to load into the **register** 1925. Two of these paths are the data and address portions of the

TIBUS

peripheral bus of Fig. 52 and . . . portion is designated 1935 and the address portion is designated 1937 in Fig. 78. The third path called the communication **register** bus 1939 is connected to a communication **register** 1941. The . . . circuitry 1216 is further described in connection with an example of simulated peripheral accesses. The device 11 suitably parallel-loads the **register** 1925 via MUX 1931 when a peripheral access or other outbound communication is commenced. Host computer 1101 scan up-loads the contents of **register** 1925, and then determines the expected response of the absent peripheral by simulation computations. Host computer 1101 then scan down-loads the simulated response of the absent peripheral into the **register** 1925. This information in **register** 1925 includes the data which would be returned from the absent peripheral in response to a Read. To convey the data to the peripheral bus, **register** 1925 is selected by a MUX 1945 to be loaded into a communication **register** 1941. Communication **register** 1941 then supplies the data through a MUX 1955 and then an output buffer 1947 onto the data bus portion. . . . MUX . . . communications outward bound on TI data bus 1935 reach

MUX

1945 at an input 1951 and are communicated via communication **register** 1941 through communication **register** bus 1939 and MUX 1931 to the 16-bit data **register** 1925. MUX 1955 selects either the communication **register** bus 1939 or an additional bus 1961 directly connected to data **register** 1925. In this way, data can be even more directly communicated from **register** 1925 via path 1961, MUX 1955 and output buffer 1947 to the TI data bus.

Buffer status flags are communicated from hardware 1965 of device 11 along with Read/Write- signal R/W- to CMD/STATUS **register** 1923 for scan out to host computer 1101. The host computer receives these buffer status flags and returns reply command. . . . Some of the command bits from **register** 1923 are communicated to a command decoder CMD DEC 1971. Decoder 1971 decodes the commands and selectively activates operation output. . . . aspects, MUX 1945 has an input 1951 connected to the data portion of the peripheral bus TIBUS for further flexibility. **Register** 1925 is connected to interrupt generation block 1943 so that even the interrupt status of device 11 can be scan. . . .

It is to be emphasized that functional clock FCLK operates when data

is

loaded into **register** 1925 from the device 11 peripheral bus and when buffer status flags are loaded into **register** 1923. Test clock JCLK operates when the data in registers 1923 and 1925 are scan up-loaded to host computer 1101, and when data is scan down-loaded to these two registers. Then functional FCLK operates to send data from **register** 1923 to command decoder 1971 and to send data from **register** 1925 to the MUXes, registers and buffers and buses of the message passing circuitry and the rest of device 11. . . .

A **register** UID 1981 is connected to the data bus 1935. A further **register** JID 1983 is connected to the data **register** 1925. The outputs of registers UID and JID are

supplied to task identification compare circuit at 1985. When the identification . . .

In . . . occurs, the monitor communicates with the emulation host computer 1101 through a TIBUS peripheral such as message passing circuitry 1216 register 1925 having an address that resides in the TIBUS address space. Once a trap has been taken and until a . . .

A . . . the address and the type of access (read or write). The emulation controller 1101 then provides the data through a register 1925 on reads or reads the data directly off the data bus on writes. READY signals for the completion of the cycle are also provided serially through the scan path to register 1923. After the appropriate transfers take place, the CPU core of device 11 is restarted.

The . . . provided task ID is implemented through the Message Passing Peripheral. The user's program provides a task ID through a TIBUS register value. This value is compared to a value loaded via scan. The comparison is enabled via an extra bit which. . .

The register 1923 in Fig. 78 is implemented as a 3 bit opcode, a four bit status field, and a nine bit. . .

The . . . 1943 of Fig. 78.

3. The TIBUS peripheral bus can be programmed by scan to Read and Write to register 1925 when no frame recognizes a select.

4. The TIBUS peripheral bus can be programmed via scan to stop. . . the core and device with the second cycle of the bus active, allowing the host 1101 to load or unload register 1925 and obtain address and a read/write indicator.

5. Restart the device execution from the message passing circuitry 1216 register 1923.

Each . . . the TI bus address and the TI bus block is addressed during simulation pipe freeze with simulated peripheral access in register 1923 enabled, the core stops before the second cycle of the peripheral access is complete. In this mode, reads are. . . no other frame is decoded. All writes are directed at the message peripheral. When the simulated peripheral access bit in register 1923 is enabled, four status bits are used to specify the number of wait states associated with the peripheral access.. . .

In category 1 the embedded microcontroller CPU execution ceases for application purposes and the CPU transfers data, for example, to the host computer 1101. Host computer 1101 does memory reads and. . .

In Category 2 (concurrent execution) a message passing peripheral MSGPASS 1216 of Figs. 52, 54 and 78 is included in the preferred embodiment combination. Advantageously MSGPASS 1216 allows the microcontroller to execute other tasks after calling the host computer 1101 for service. Then code from the application system is sent via the scan serial line 1103, and inserts interrupts over EMU0 line to software control to make. . .

Block transfers are accomplished by use of the message passing peripheral 1216 by loading the register 1925 from communication register 1941, and with JTAG controller in the IDLE state, do N (e.g 16) bit serial shift, and then cycling back to load register 1925 again. The block transfers can be directed to any other serial interface to which the scan path is connected.. . .

The . . . is advantageously further useful for development system purposes. Host computer 1101 operating as a development system downloads a command to register 1923 requesting the machine state of the embedded microcontroller. The microcontroller responds by trapping (analogous to an interrupt) to prestored. . .

A . . . of a GSP chip 2120 having a central processing unit 2200 connected by buses 2202, 2204, 2206 and 2208 to register

files 2220, instruction cache 2230, host interface 2240 and graphics hardware 2216 respectively. A further bus 2205 interconnects a host.

For . . . testability, the GSP 2120 memory elements are split into two types:

(1) Multiple-bit registers such as those in the register file 2220, the Cache RAM 2230, a memory address register 2103, memory data register 2105 and a field size register 2107. These are all on wide buses, and sufficient logic is included to ensure that there is a route from. . . these registers to local address data (LAD) pins of the chip.

(2) Serial latches, such as an emulation control register 2121, buffer SRLs 2135 of a control ROM (CROM) 2131, and scanable registers of core processing circuitry 2101 on chip. . . One approach to testability herein is called parallel serial scan design (PSSD). A rule is imposed in which every register bit and serial latch are only loaded by some function ANDED with, or conditional on, a single clock phase (H3T). . . Each parallel register cell has a circuit shown in Fig. 83. It is loaded on the (normally conditional) H3T phase and is sampled on a (conditional) H1T phase. Control logic and microcode are included on-chip to enable every parallel register to be loaded and dumped onto the LAD bus. Thus, the machine state can be loaded up, executed, and then. . .

A circuit for each serial latch is shown in Figure 84. It is similar

in

form to the parallel register circuit of Fig. 83, but contains an additional serial input called the scan input Scan In. For the purposes of. . .

A memory address register MA 2103, a memory data register MD 2105 and a field size register 2107 are associated with main core 2101. A four wire scan interface or port

2111

is connected to a selecting. . . pins. Emulation control pins EC0 and EC1 provide further control inputs. Selecting circuit 2112 is connected to an emulation control register 2121.

Register 2121 is also called a scan control register herein. Special test TST and Compress COM bits 0 and 1 in register 2121 are connected to selector circuit 2112 to route the lines 2115 and 2117 to one of three scan paths. The first path allows scan to register 2121 itself. The second path allows scan of CROM buffers 2135 and core 2101. The third path connects to

a.

A register select code is supplied by emulation control register 2121 bits 2-5 SCAN SEL on a line 2125 to control the MUX 2113. In this way, register selection of a selected one of registers 2103, 2105 and 2107 is controlled by emulation control register 2121 in its operation of MUX 2113. Scan data in and data out on lines 2115 and 2117 are thus. . . Test modes are controlled via the EC1, EC0 and SCIN pins, and two bits TEST and COMPRESS of the emulation control register 2121. The . . . define the state of the emulation control port. Scanning

a

1 into the TEST bit zero (0) of the control register 2121 redefines the port as a test control port as long as a code 111 (for EC1, EC0 and SCIN). . . to the interface 2111. The 111 code is a normal user run mode and also clears the entire emulation control register 2121, including the TEST bit, thus resetting the port.

The relationship of the codes to the MPSD codes tabulated earlier. . .

In Fig. 81 control ROM (CROM) 2131 is connected to main CPU 2101. The second bit COMPRESS of the emulation control register 2121 extends the possible number of test states available via the interface

and is used for CROM compressions in a type testing called signature analysis. In such signature analysis, a scanable linear feedback shift register 2141 of Fig. 86 is combined with the CROM buffers 2135 of Figs. 81 and 85 and is used to. . . . In Fig. 86, the scanable linear feedback shift register 2141 utilizes a data compression method of self-testing the CROM. The method

accesses every state. For each access, a word. . . . A stack register 2145 in normal operation is used during micro-state pops and pushes in the circuit of Fig. 85. In CROM test mode this register 2145 is reused as a 13-bit counter. The two most significant bits of the counter are used to control whether.

The . . . compression on CROM output:

SCANCOMP - PLOAD - SCAN(I) - CROM - SCAN(O)

SCANTEST means "Scan TEST bit into control register".

SCANCOMP means "Scan TEST and COMPRESS bits into control register".

SCAN is a simultaneous scan in and scan out. Scan(I) implies the scan is scan-in for data initialization. SCAN(O) implies. . . . In . . . 111 is applied for two cycles to exit the test mode and clear the entire contents of the scan control register. If the TEST bit is set, the first cycle clears only the test bit. In the second cycle, the code 111 and the cleared TEST bit then clears the rest of the scan control register 2121. In this way, exit occurs from the test mode into an emulation mode such as an emulation controlled run.. . . .

Using . . . modification, inspect and/or alter, while the processor is in stop mode without change to user environment. This includes internal (I/O register) and external memory spaces.

Inspection and/or modification while in stop mode is also performed. Modification of all internal registers including PC (program counter), ST(status register), and SP (stack pointer) while in stop mode is also available.

3. Single stepping of instructions.

Internal state information utilized by the emulator host computer 1101 of Fig. 45 includes the program counter PC, the register file of CPU 2101 and cache, segment registers and p-flags.

The . . . at the pins EC1, EC0 and SCIN are as follows: Normal functional mode, controlled execution mode, halt, pause, emulation control register scan and scan of data registers 2103, 2105 and 2107. See Table VI. These codes are essentially the MPSD codes. . . .

All . . . registers are scanned in through the LSB (least significant bit) and out through the MSB (most significant bit). Emulator control register 2121 is scannable in response to the Table VI code "emulation control register scan" applied to pins EC1 and EC0.

The . . . power up. Reset is a global signal within the chip. The functional run mode code continuously clears the emulation control register 2121.

The . . . such as load and dump. In this mode, reset is gated with

a Block Reset bit in the emulation control register. The emulation control register 2121 is not cleared on reset in this mode.

The . . . initiated memory cycles to complete. Second, the CPU stores the contents of the program counter PC in the memory data register 2105. Third, the CPU signals the stop by generating a STOPACK signal, forcing scan out line SCOUT low. Fourth, the . . . The scannable registers are memory address register 2013, memory data register 2105 and field size register 2107. Register 2103 and 2105 each have 32 bits, For example,

the field size **register** 2107 is 6 bits. The **register** to be scanned is determined by a data scan select field (bits 2-5) of the emulation control **register** 2121. The microcode in the CROM accomplishes four main functions on command. First, it transfers data from a selected device **register** or from cache or from program counter to the memory data MD **register** 2105. Second, it transfers from the MD **register** 2105 to a selected device **register** or to cache or to program counter. Third, it executes MPSD code to do step-by-step operations. Fourth, it sends instructions to the memory interface 2250 to transfer data either way between external memory

and

the **register** pair MD 2105 and MA 2013.

Memory address **register** 2103 holds the address for all CPU initiated memory accesses including those of the emulator. After a memory access is completed, **register** 2103 is incremented by 32 bits to point to the next word address. The low 5 bits are left unchanged. . . . contents are loaded into the upper 28 bits and the halt condition code occupies the low four bits of this **register**

Memory data **register** 2105 passes data between the emulator and memory controller. **Register** 2105 serves as a data latch for passing data between the emulator and the CPU for loads and dumps. When the CPU is initially halted, this **register** 2105 contains an image of the CPU program counter and a halt code in the low order four bits. This. . . .

The field size **register** 2107 makes it possible to do memory accesses to data fields of various sizes specifiable by the field size **register**.

The value loaded into **register** 2107 is a 6 bit code that indicates the number of bits to be written. Using **register** 2107 permits the emulator to write to bits or fields without having to do a read-modify-write operational sequence, which could. . . host computer access operations occurring between the read and write of the sequence. When the CPU is initially halted, the **register** 2107 contains an indeterminate value, since it is the actual latch and not

a

copy. Scan in of a value into **register** 2107 enters the value in the most significant 6 bits of **register** 2107. Upon scanning out the value, the value is in the least significant 6 bits of **register** 2107.

The emulation control **register** has bits as specified in Table IX. The contents of emulation control **register** 2121 are not executed until control scan mode is changed to another MUX. <image> <image> Four bits 2-5 in the emulation control **register** 2121 select one of the registers 2103, 2105 and 2107 for serial scan during Data Register Scan mode. During normal functional mode, these four bits are cleared to zero. Table X shows the scannable registers and.

The . . . a set of functions that are tabulated in Table XI. The proper function code is placed in the emulation control **register**. The processor CPU 2101 is then placed in the controlled run mode. The CPU 2101 then forces line SCOUT high, . . .

The bits FCN3, FCN2, FCN1 and FCN0 occupy bits 9-6 of the emulation control **register** 2121.

In . . . dump. The CPU 2101 then fetches the requested parts of the machine state and loads them into the memory data **register** 2105 one by one. For each group of 32 bits, the emulator host computer 1101 scans out memory data **register** 2105 serially to obtain the data. More specifically, the operation for emulator dump is as follows. First, the emulator scans. . . Table XI to dump the state using the control scan mode and sets the emulator busy enable bit 10

of register . . . 1. Second, the emulator enters a controlled execution mode. Third, the CPU 2101 forces SCPOUT pin high. Fourth,

the

CPU 2101 places a 32 bit word of the machine state in **register** 2105 and forces SCOUT pin low. Fifth, CPU waits for the cycle to complete. When emulator busy bit is enabled, . . . signals stop acknowledge STOPACK on the SCOUT pin low. Sixth, the emulator enters a data scan mode and scans the **register** 2105. When scanning, the CPU 2101 is inhibited from concurrent activity in this embodiment. Seventh, operations return to step two. . . .

The end of the process is determined by the known number of words to dump. After dumping the cache and the **register** file, an extra controlled run is executed after the last word has been scanned out so that the CPU can. . . .

The emulator then clears the emulator busy bit in the emulation control

register 2121.

For example, in the function DUMP ST,PC, the "1000" function code causes the CPU program counter and status **register** to be dumped. The status **register** is dumped first, followed by the PC.

In the DUMP REG.FILE function, the "1001" function code causes the A and B **register** files to be dumped in that order.

In . . . load functions, designated by codes 1011, 1100 and 1101, the emulator scans in a load request and values into the **register** 2105. CPU 2105 then builds the machine state from values in **register** 2105. First, the emulator scans in the code to load the state using the emulation control **register** scan mode and then sets the emulator busy bit. Second, the emulator scans in **register** 2105 using the data **register** scan mode. Third, the emulator enters the controlled execution mode, and fourth, the CPU 2101 forces line SCOUT high. Fifth, . . . the data has been loaded, line SCOUT is forced low. Sixth, the emulator scans a succeeding 32 bit word into **register** 2105. Exiting the data scan **register** mode clears the busy flag. Seventh, operations return to the third step of entering the third execution mode. The

end.

. . . load which is a predetermined number. The emulator then clears the emulation busy enable bit 10 in the emulation control

register 2121.

In the LOAD PC,ST function, the 1011 function code causes the status **register** to be loaded followed by the CPU program counter. In the LOAD REGS 1100 function code, the A and B **register** files are loaded in that order. In the LOAD CACHE function 1101 code, the cache is loaded starting with segment. . . .

The emulator can access any part of the chip address space including I/O registers by scanning in address values to **register** 2103 and data values to **register** 2105, together with a memory read or write function code to emulation control **register** 2121.

When the CPU is in the emulator halt state, these registers are available to the emulator and the controlled. . . . code using this mechanism, the emulator flushes the cache by setting the cache flush bit 29 in the emulation control **register** 2121.

The functions of the bits of emulation control **register** 2121 (which is analogous to emulation control **register** 1251 of Fig. 59) are now discussed in even further specific detail. If emulation busy enable bit 10 is set. . . .

Load . . . During normal functional mode, this bit is cleared to zero. The emulator insures that the "data" part of the MA **register** 2103 contents is not contained in the least significant five bits as these bits of the **register** 2103 are not output to the LAD bus. The emulator insures that the least significant five bits are loaded with. . . .

A single step control bit 16 in the emulation control **register** 2121 causes core 2101 to execute only one instruction before generating

a stop acknowledge STOPACK signal on the SCO pin. . . .
instruction
into the instruction stream after the current instruction. This bit ORED with the single step bit in the status register before going to the microcontroller. During normal functional mode, this bit is cleared to zero.
A . . . CPU 2101 inserts a code 1111 (halt due to bus fault) on the least significant four bits of memory address register 2103, along with the contents of the program counter.
A single step mode bit 16 in the emulation control register and a similar bit in CPU 2101 status register, control CPU function for single step. When either of the single step bits are set to "1", the CPU halts.
Interrupt logic associated with core 2101 monitors for interrupts regardless of the state of the emulation control register 2121. Thus, the state of an INTPEND IO register will be the same as if the core 2101 has interrupts masked for any HALT/SCAN periods. On a transition into run or single step with the interrupt enable bit of the status register set, the highest priority pending interrupt is taken. In this way, the interrupt enable bit is cleared of status which. . . .
The . . . 1203. In addition, as will be apparent from the following description, the lock control circuitry at 1401 and the LOCK register 1351 can be eliminated from the adaptor 1203. As will also be apparent from the following description, any two of. . . .

=> d ab 5

L6 ANSWER 5 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

=> d ab 5

L6 ANSWER 5 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

=> d ab 6

L6 ANSWER 6 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

=> d ab 7

L6 ANSWER 7 OF 32 EUROPATFULL COPYRIGHT 2000 WILA

=> d ab 8

L6 ANSWER 8 OF 32 PROMT COPYRIGHT 2000 IAC

- AB At the Windows Hardware Engineering Conference (WinHEC) in San Francisco last month, Microsoft demonstrated a virtual racing car. Like a ground-borne aircraft flight simulator, this machine would give drivers all the visual and auditory excitement of a race car turning the track at 160 or 180 mph-as well as the corresponding drags, pulls and bumps in the steering column and pedals. "This would be useful for race car driver training," a smiling Bill Gates told an audience of 4,000. And in the WinHEC exhibition, aisle after aisle of hardware manufacturers demonstrated what they were doing to promote similar entertainments on

Windows platform. It was a virtual funhouse of dazzling 3-D graphics effects, streaming video windows and dramatic positional sound effects. The demonstrations at WinHEC seemed to verify that home entertainment-Windows games and Digital Versatile Disk (DVD) playback systems-would still be the primary application for analog and mixed-signal

ICs developed to serve audio, video and multimedia. While 3-D data visualization for financial analysis might be appropriate business applications of 3-D graphics, suggested graphics industry analyst John Peddie Associates (Tiburon, Calif.), it will probably be 2005 before 3-D graphics and animation are used outside of PC games and movies.

Similarly, Mike Feibus of Mercury Research (Phoenix) sees business audio applications as a distinct possibility for 1998. But few people now have

a clear idea of what the most dramatic business applications would be.

While

3-D graphics could be used for data visualization for financial analysis, suggested Chris Henningsen, a marketing manager with Harris Corp. (Melbourne, Fla.), that might depend on multimedia's ability to record audio and video, to packetize it for delivery over phone lines, corporate networks or the Internet. Thus, there is related development in video capture devices, A/D converters for audio, or, in Harris' case, videoconferencing components. But the bulk of graphics, video and audio controllers are being developed to support a \$1.2 billion Windows games industry.

The most dramatic of these mixed-signal devices are "accelerators" for both 3-D graphics and audio, which offload multimedia processing tasks from the host CPU.

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=> d ab 9

L6 ANSWER 9 OF 32 USPATFULL

AB The invention provides improved architectures and methods for emulation,

simulation, and testability of data processing devices and systems without requiring physical probing or special test fixtures. A data processing device may include a semiconductor chip that is divided into domains. One domain may be halted and tested while another domain continues to operate. For example, the semiconductor chip may have a electronic processor domain and an analysis domain. The analysis domain may include an on-chip condition sensor that is connected to the electronic processor domain. The chip can further include control logic circuitry to allow the analysis domain to operate while the electronic processor is halted and tested.

=> d kwic 9

L6 ANSWER 9 OF 32 USPATFULL

SUMM In addition to testing for functionality and for manufacturing defects, application software development requires a similar level of simulation, observability and controllability in the system or sub-system design phase. The emulation phase of design should ensure that an IC (integrated circuit), or set of ICs, functions correctly in the end equipment. . . .

SUMM . . . simulation and continually increasing cost of CAD (computer aided design) tools. In the board design the side effects include decreased register visibility and control, complicated debug and simulation in design verification, loss of conventional emulation due to loss of physical access by packaging many circuits in one package, increased routing complexity on the board,

increased costs of design tools, mixed-mode packaging, and design for producability. In **application development**, some side effects are decreased visibility of states, high speed **emulation** difficulties, scaled time simulation, increased debugging complexity, and increased costs of **emulators**.

Production side effects involve decreased visibility and control, complications in test vectors and models, increased test complexity, mixed-mode packaging, continually.

SUMM Among the objects of the present invention are to provide improved **emulation**, simulation and testability architectures and methods which provide visibility and control without physical probing or special

test fixtures; to provide improved **emulation**, simulation and testability architectures and methods which are applicable to critical components of system designs to support test and integration of both hardware and software; to provide improved **emulation**, simulation and testability architectures and methods that are a viable alternative to high capital-cost test equipment and systems; to provide improved **emulation**, simulation and testability architectures and methods which integrate access to sophisticated operations in hardware **emulation**, fault **emulation**, simulation and built-in test; to provide improved **emulation**, simulation and testability architectures and methods which apply hardware and software visibility and control to reduce **application**

development time and thus reduce the user manufacturer's time-to-market on new products; and to provide improved **emulation**, simulation and testability architectures and methods to leverage hierarchical partitioning and automatically generate reusable tests for related chips and systems.

DRWD FIG. 16A is a compact diagram of shift **register** latches SRLs in a scan chain in FIG. 16;

DRWD FIG. 40 is a schematic of a parallel **register** latch for use in the GSP chip of FIG. 37;

DRWD FIG. 41 is a schematic of a serial **register** latch for use in the GSP chip of FIG. 37;

DETD Extended development system 1101 provides full-speed, in-circuit **emulation** for system design and for hardware and software debug on widely available personal computer systems. The development tools provide technological. . . to prototype. The development system elements provide ease of use and offer the designer the tools needed to significantly reduce **application system development** time and cost to put designs into production faster.

DETD . . . configuration file, a GSP (graphic signal processor) configuration, a programmable array logic (PAL) file, an ASIC file and a

a **GPL register** file.

DETD . . . software and hardware with the target system. An important emulation interface provides control and access to every memory location

and **register** of the target chip and extend the device architecture as an attached processor.

DETD . . . before the target system is complete. To accomplish this, code is downloaded into the memory on the board 1043 and **executed** at full speed via the interface on an **application** board used in place of the incomplete target system. A suitable **application** board includes a DSP 11, 16 K.times.32 bits of full-speed (zero wait states) BRAM on a primary bus, two selectable. . .

DETD . . . coassigned application Ser. No. 06/057,078 (TI-12033) issued Aug. 22, 1989, (U.S. Pat. No. 4,860,290) and incorporated herein by reference. Shift **register** latches (SRLs) designated "S" are distributed through the device 11 like a string of beads on a serial scan path. . .

DETD . . . TDO communicate with the system. TMS and TCK communicate with a tap controller 1151 which is connected to an instruction

register 1153 an instruction decoding circuit 1155.

DETD Test access port (TAP) controller 1151 is in turn coupled to instruction

register (IR) 1153 and a first multiplexer 1173. The instruction register can receive serial scan signals from the TDI line and output serially to MUX 1173. MUX 1173 is under control of the TAP and can select the output signal from the instruction register or from another MUX 1171.

DETD The instruction register also controls a bypass

register (BR) 1167 and one or more boundary scan registers (BSR) 1161. The bypass register receives the TDI signal and outputs it to MUX 1171. MUX 1171 is under control of the instruction register 1153. Based on the instruction loaded into the instruction register, MUX 1171 outputs its input from the bypass register or its input from one or more BSRs, or internal device register scan. Each boundary scan register is controlled via the test access port and the instruction register.

DETD . . . or a test mode. During the normal mode, input data entering terminals of IC logic passes through the boundary scan register, into the IC logic and out to the normal output terminals without any change due to the BSR. During the . . . test mode, normal input data is interrupted, and test input data is captured, shifted, and updated within the boundary scan register. The boundary scan register includes two memories, a first memory for receiving and shifting data from the TDI line and a second memory for. . .

DETD . . . controller card 1141 through pin TDI and enters any one of a number of shift registers, including a boundary scan register 1161, a device identification register 1163 and design specific test data registers 1165. A bypass register 1167 is also provided. These shift registers or serial scan registers are selected via a MUX 1171 under the control. . . output from MUX 1171 is fed to a MUX 1173 so that under control of tap controller 1151 the instruction register 1153 or MUX 1171 is selected by MUX 1173.

JTAG clock TCK and MUX 1173 output are fed to flip. . .

DETD . . . has two scan paths. One of the scan paths is termed the MPSD data path which usually has numerous shift register latches S (or SRL) serially interconnected like a string of beads throughout the module. The second scan path is termed the MPSD control path which generally has fewer shift register latches and which selects which MPSD data paths are to be scanned. These scan paths are described in above-cited application. . .

DETD . . . core domain 1213, system domain 1215 and analysis domain 1217 are shown in FIG. 7 and interface through the shift register latches of FIG. 4 to all of the various parts of the chip.

DETD . . . chip of device 11. JTAG control 1201 interfaces with the pins via a serial boundary scan assembly including boundary scan register 1161 which allows all logic states at the actual pins of device 11 to be read or written. JTAG TAP controller 1151 and JTAG instruction register IR 1153 are provided on-chip. Test control 1205 and MPSD control 1203 are integrated into the circuitry . MPSD control. . .

DETD . . . as the following five distinct clocking domains in order to control domain data transfers with the scan clock (JCLK) and application execution with the functional clock (FCLK).

DETD . . . data is scanned to and from the device 11 through internal scan

paths that are selected through a JTAG instruction register 1153. A unique JTAG opcode for each path allows entry of and access to internal scan data.

DETD FIG. 11 shows a further diagrammatic respective of the registers of FIG.

7 wherein JTAG instruction register IR 1153 is selected for scan between the terminals TDI and TDO. The IR 1153 is decoded in FIG.

7. . . requested by the control card 1141 of FIG. 2 via the serial line 1103. These shift registers are the bypass register 1167, the boundary scan register 1161, the message peripheral 1216 of FIG. 9, the emulation control register 1251 and a pair of MPSD scan paths 1252 in the various domains and modules in the domains.

DETD . . . when not scanning and a zero when scanning. CO and CX are sourced from the emulation control block adapter 1203 register 1251. When host computer 1101 detects Ready to scan for all unlocked domains for a designated device on the target. . .

DETD in . . . mode conditioned stop logic circuitry 1309B, 1309C and 1309A

the domains respectively. The modes are established by a mode register 1311 which is scanable in FIGS. 11 and 14 to establish the type of stop and any other desired mode. . .

DETD . . . sent to the CPU domain 1213 to make it stop according to the stop mode established for it in mode register 1311 and mode conditioned stop circuitry 1309C. DONE circuitry 1363 detects when the stop is completed and signals back to. . .

DETD . . . an example of process steps by which the scan control 1149 including IR 1153, adapter 1203 including ECR (emulation control register) 1251, and host computer 1101 cooperate to enter and perform sequences of commands on-chip.

DETD . . . to reach the state "Select-DR-Scan". This means that the scan controller is ready to accept scan into

<-----User Break----->

u
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=> d 9

L6 ANSWER 9 OF 32 USPATFULL
AN 2000:25940 USPATFULL
TI Processor condition sensing circuits, systems and methods
IN Swoboda, Gary L., Sugar Land, TX, United States
Ehlig, Peter N., Houston, TX, United States
PA Texas Instruments Incorporated, Dallas, TX, United States (U.S.
corporation)
PI US 6032268 20000229
AI US 1992-832661 19920204 (7)
RLI Continuation of Ser. No. US 1989-388286, filed on 31 Jul 1989, now
abandoned And a continuation-in-part of Ser. No. US 1987-93463, filed
on 4 Sep 1987, now abandoned Ser. No. Ser. No. US 1987-140055, filed on 31
Dec 1987, now patented, Pat. No. US 5109494 Ser. No. Ser. No. US
1987-140192, filed on 31 Dec 1987, now patented, Pat. No. US 5101498
Ser. No. Ser. No. US 1989-347968, filed on 4 May 1989, now abandoned
Ser. No. Ser. No. US 1989-347969, filed on 4 May 1989, now abandoned
Ser. No. Ser. No. US 1989-347605, filed on 4 May 1989, now abandoned
Ser. No. Ser. No. US 1989-347596, filed on 4 May 1989, now patented,
Pat. No. US 5072418 Ser. No. Ser. No. US 1989-347615, filed on 4 May
1989, now patented, Pat. No. US 5142677 Ser. No. Ser. No. US
1989-347966, filed on 4 May 1989, now patented, Pat. No. US 5155812 And
Ser. No. US 1989-347967, filed on 4 May 1989, now abandoned
DT Utility
LN.CNT 3972
INCL INCLM: 714/030.000
INCLS: 714/034.000; 714/726.000
NCL NCLM: 714/030.000
NCLS: 714/034.000; 714/726.000
IC [7]
ICM: G01R031-3177
ICS: G01R031-3185
EXF 371/16.2; 371/19; 371/22.3; 371/22.5; 714/30; 714/34; 714/726

=> d ab 10

L6 ANSWER 10 OF 32 USPATFULL

AB An apparatus and method for accelerating interpreters, interpretive environments, may manage pinning of a processor cache closest to a processor. An instruction set implementing a virtual machine may store each instruction in a single cache line as a compiled, linked loaded image. After loading, the cache is pinned, disabled from flushing the contents or replacing the contents of any cache line. A fast load may flush the cache and run an application containing the entire virtual machine instruction set. A pin manager may be hooked into a scheduler

in

a multi-tasking operating system to load, pin, and unpin the processor cache as rapidly as needed. Thus, the processor cache may be available for general use, except when pinned for use by a virtual machine, such as an interpretive environment. Level-1 caches integrated into central processing units, particularly instruction caches or code caches are ideally suited to implementation of the invention.

=> d ab 11

L6 ANSWER 11 OF 32 USPATFULL

AB A customizable data acquisition device (DA) and a data collection system

(DCS). The DA is remotely located for attachment to a variety of I/O devices, and uses an RF transceiver with a primary cache. A centrally located or mobile DCS with a secondary cache communicates with one or more DA's and stores DA data in the secondary cache. The DA has a programmable controller and an I/O interface capable of attaching to a variety of I/O devices. The DA primary cache holds data for bulk transfers to the DCS to minimize DA/DCS data transmission traffic. The DCS secondary cache accumulates data from the DA and allows data

queries

by multiple independent application programs (which may be located on the DCS, other DCSSs, or remote host systems) without requiring retransmission of data from the DA for each query. Applications can query cached data in the secondary cache, and optionally query the primary cache or query the I/O device via the DA. Each DA is capable of peer to peer communication to allow DAs physically located outside of the transmission range of the DA/DCS to communicate with the DCS by routing data through other DAs in a network of DAs until the data can

be

transmitted to the DCS. I/O devices and DAs are shared by multiple applications in a hierarchical network of applications, host computers, DCSSs, DAs, and I/O devices. A pass-through function allows the I/O interface to be emulated for software testing. When software testing is complete, the software is permanently stored in the DA.

=> d ab 12

L6 ANSWER 12 OF 32 USPATFULL

AB A telephone instrument with a 12-key keypad that has relegendable buttons. The telephone instrument is coupled to apparatus such as a personal computer, network server, or switch that is capable of performing telephony functions. The telephony apparatus responds to an input from the keypad by providing a new set of legends for the keys and/or performing a telephone function. In a preferred embodiment, the telephone instrument is connected both to a personal computer and to a POTS telephone circuit and includes a separate keypad for the POTS telephone circuit. The apparatus includes a component which detects a

failure in the personal computer and automatically deactivates the keypad with the relegendable buttons, leaving the telephone instrument still available for use with the POTS circuit. Also disclosed are a reduced-cost implementation of the telephone instrument and alternative embodiments in which the telephone instrument is connected to the telephony apparatus by a packet interface or itself contains the component which performs the telephony functions. The telephony functions may be those employed in switched circuit telephone systems

or

those employed in packet telephone systems, and the systems themselves may be either wired or wireless.

=> d ab 13

L6 ANSWER 13 OF 32 USPATFULL

AB A method for debugging a target application comprising Java code having native method dll's associated therewith. The method is carried out in

a

computer having an operating system, a system debug application programming interface (API), and a Java virtual machine having a Java debug API. According to the method, the Java virtual machine is first launched under the system debug API. The application is then run under the Java virtual machine. Because the Java virtual machine that runs

the

target application itself runs under the system debug API, simultaneous control of the target application via the system debug API and the Java debug API is enabled. Thus, the method effects the debug of the target application by simultaneously debugging the Java code and the native method dynamic load libraries.

=> d 13

L6 ANSWER 13 OF 32 USPATFULL

AN 1999:54524 USPATFULL

TI Method for debugging a Java application having native method dynamic load libraries

IN Edwards, Jonathan W., Lexington, KY, United States

Evans, David H., Lexington, KY, United States

Vassil, Michael G., Lexington, KY, United States

PA International Business Machines Corporation, Armonk, NY, United States
(U.S. corporation)

PI US 5901315 19990504

AI US 1997-874644 19970613 (8)

DT Utility

LN.CNT 683

INCL INCLM: 395/704.000

INCLS: 395/701.000; 395/183.140; 395/183.010; 395/406.000; 395/500.000;
395/527.000; 395/682.000

NCL NCLM: 395/704.000

NCLS: 395/500.430; 395/527.000; 395/701.000; 709/001.000; 709/302.000;
709/305.000

IC [6]

ICM: G06F009-44

ICS: G06F011-00

EXF 395/704; 395/701; 395/183.14; 395/183.13; 395/183.1; 395/183.01;
395/185.01; 395/682; 395/500; 395/650; 395/406; 395/527

=> d ab 14

L6 ANSWER 14 OF 32 USPATFULL

AB An apparatus and method for accelerating interpreters, interpretive environments, and the like optimizes the use of caches closest to a processor. An instruction set implementing a virtual machine (interpreter, interpretive environment) is written to fit each instruction at an individual cache line's address in the processor cache. The processor cache may be loaded with the instruction set in a compiled, linked, loaded image. After loading the processor cache, the cache is pinned, locked, disabled from flushing the contents or replacing the contents of any cache line. Faster loading of the processor cache may be achieved by flushing the processor cache and running an application containing all of the instructions of the virtual machine instruction set. Level-1 processor caches integrated into central processing units, particularly instruction caches or code caches are ideally suited to implementation of the invention. Examples include Intel's Pentium.TM. class products and Motorola's Power PC Processors.

=> d ab 15

L6 ANSWER 15 OF 32 USPATFULL

AB A method for testing a digital processor 11 in which a test port 1149 is used to transfer trace data from the digital processor to a test host processor 1101 under control of a user definable program which executes in response to predetermined events on the digital processor. Trace data is gathered while an application program loaded in program memory 61 is executed by the digital processor. Trace data is temporarily stored in a trace region 99 of data memory 25 by user definable code which is executed in a background manner by the digital processor in response to trigger events. The trigger events are also enabled by user definable code which enables various portions of analysis hardware 1217. Trace data is transferred from the digital processor to the test host processor through test port 1149 by sending a notification signal to the test host processor by means of message passing register 1216. The digital processor then monitors the message passing register for a handshake signal from the test host processor. When a handshake signal is received, trace data is written into the message passing register by user definable code in a background manner and transferred to the test host processor.

=> d ab 16

L6 ANSWER 16 OF 32 USPATFULL

AB An emulation device (11) distributes common control information (8801) to each of a plurality of clock domains (1213, 1215, 1217) into which the emulation device is partitioned, and also provides the clock domains with individualized clock control (8905, 8907, 8913).

=> d ab 17

L6 ANSWER 17 OF 32 USPATFULL

AB A system and method for performing an emulation context switch save and

restore in a processor that executes host applications and emulates guest applications. The processor includes an operating system and a first register that is saved and restored by the operating system during a host application context switch. The method and system comprises renaming the special-purpose register to the first register when emulating guest applications. When an emulation context switch occurs, a context save and restore of the special-purpose register is performed through the first register without operating system modification.

=> d kwic17

'KWIC17' IS NOT A VALID FORMAT

In a multifile environment, a format can only be used if it is valid in at least one of the files. Refer to file specific help messages or the STNGUIDE file for information on formats available in individual files.

REENTER DISPLAY FORMAT FOR ALL FILES (FILEDEFAULT):end

=> d kwic 17

L6 ANSWER 17 OF 32 USPATFULL

AB A system and method for performing an emulation context switch save and restore in a processor that executes host applications and emulates guest applications. The processor includes an operating system and a first register that is saved and restored by the operating system during a host application context switch. The method and system comprises renaming the special-purpose register to the first register when emulating guest applications. When an emulation context switch occurs, a context save and restore of the special-purpose register is performed through the first register without operating system modification.

SUMM The assignee of the present application has developed hardware that assists software emulation methods in order to obtain a solution that has the positive characteristics of both methods:
the small size of the interpreter and the speed of execution of the dynamic translator. Before the assisting hardware is used, the sequence of host instructions necessary to perform the function. . .

SUMM . . . This is referred to as a context save. When the process is subsequently swapped-back in, the operating system restores the register contents. This is referred to as a context restore.

SUMM The present invention is method and system for performing an emulation context switch save and restore in a processor that executes host applications and emulates guest applications. The processor includes an operating system and a first register that is saved and restored by the operating system during a host application context switch. The method and system comprises renaming the special-purpose register to the first register when emulating guest applications. When an emulation context switch occurs, a context save and restore of the special-purpose register is performed through the first register without operating system modification.

DETD . . . such as multiply, add, divide, and multiply-add. The FPRs 102 are used to store the values generated by a floating-point application as the application executes.

DETD When a floating-point application is swapped-out during a context switch, the operating system 104 performs a context save on

those FPRs 102 used by the application as follows. When another application is swapped-in that subsequently executes a floating-point instruction, the floating-point instruction causes what is known as a floating-point not available (FPNA) exception. The FPNA exception is an interrupt that causes the operating system 104 to save the contents of the previous application and to reset the FPNA so that the new application can use the FPRs 102.

CLM What is claimed is:

1. A method for performing emulation context switch save and restore in a processor that executes host applications and emulates guest applications, the processor including an operating system and a first register that is saved and restored by the operating system during a host application context switch, the method comprising the step of: (a) renaming a special-purpose register to the first register when emulating guest applications, wherein a floating-point register is provided as the first register; and (b) performing an emulation context switch, wherein a context save and restore of the special-purpose register is performed through the first register without operating system modification.

. . . as in claim 2 wherein step (a) further includes the step of: (a2) associating a direction bit with the special-purpose register and the floating-point register to indicate whether the special-purpose register or the floating-point register contains the most current value.

. . . claim 3 wherein step (b) further includes the step of: (b2) setting the direction bit to indicate that the special-purpose register contains the most current value.

. . . claim 4 wherein step (b) further includes the step of: (b3) resetting

the direction bit to indicate that the floating-point register contains the most current value.

. . . step (b) further includes the step of: (b4) when performing an emulation context store, storing the contents of the special-purpose register if the direction bit is set, and storing the contents of the floating-point register if the direction bit is reset.

. . . claim 6 wherein step (b) further includes the steps of: (b4) when performing an emulation context restore, loading the floating-point register and the special-purpose register; and (b5) resetting the direction bit.

8. A method as in claim 7 wherein a pair of special-purpose registers is renamed to the floating-point register.

9. A processor that executes host applications and emulates guest applications, the processor comprising: an operating system; a first register that is saved and restored by the operating system during a host application context switch; a special-purpose register; means for renaming the special-purpose register to the first register when emulating guest applications, wherein the first register is a floating-point register; and means for performing an emulation context save and restore of the special-purpose register through the first register without operating system modification, wherein the means for performing an emulation context save and restore of the special-purpose register are user-level instructions.

11. A processor as in claim 10 further including a direction bit associated with the special-purpose register and the

floating-point register to indicate whether the special-purpose register or the floating-point register contains the most current value.

12. A processor as in claim 11 wherein the direction bit is set to indicate that the special-purpose register contains the most current value.

13. A processor as in claim 12 wherein the direction bit is reset to indicate that the floating-point register contains the most current value.

. . . context store is performed, if the direction bit is set, then the operating system stores the contents of the special-purpose register, and if the direction bit is reset, then the operating system stores the contents of the floating-point register.

. . . A processor as in claim 14 wherein when an emulation context restore is performed, the operating system loads the floating-point register and the special-purpose register, and resets the direction bit.

16. A processor as in claim 15 wherein a pair of special-purpose registers is renamed to the floating-point register.

17. A processor for executing host applications and emulating guest applications, each of the guest applications including guest instructions, the . . . a plurality of floating-point registers for containing values, wherein each pair of special-purpose registers are renamed to a particular floating-point register; and a direction bit associated with each pair of special-purpose registers

and

the corresponding floating-point register to indicate whether the pair of special-purpose registers or the corresponding floating-point register contains the most current value; wherein the operating system is responsive to the direction bit to perform an emulation context. . . .

=> d 17

L6 ANSWER 17 OF 32 USPATFULL
AN 1998:117089 USPATFULL
TI Method and system for performing an emulation context save and restore that is transparent to the operating system
IN Kahle, James Allan, Austin, TX, United States
Mallick, Soummya, Austin, TX, United States
Martin-de-Nicolas, Arturo, Austin, TX, United States
PA International Business Machines Corporation, Armonk, NY, United States
(U.S. corporation)
PI US 5812823 19980922
AI US 5817943 19960102 (8)
DT Utility
LN.CNT 391
INCL INCLM: 395/500.000
INCLS: 395/563.000; 395/569.000; 395/570.000
NCL NCLM: 395/500.470
NCLS: 395/500.480; 712/222.000; 712/228.000; 712/229.000
IC [6]
ICM: G06F009-455
EXF 395/500; 395/563; 395/567; 395/569; 395/570; 395/527; 395/385; 395/580;
395/584

=> d ab 18

L6 ANSWER 18 OF 32 USPATFULL

AB An electronic device having addressable storage elements and a bus so that the storage elements are accessible via the bus, an address register connected to the bus, a data register connected to the bus, terminals for serial scan-in and scan-out, a scanable emulation control register coupled to the terminals, and a selecting circuit responsive to bits in the emulation control register for coupling the address register and the data register to the terminals to enable scanning of the address and data registers.

=> d ab 19

L6 ANSWER 19 OF 32 USPATFULL

AB Telephone station equipment consisting of a phone device interconnected with a personal computer. The phone device includes a conventional telephone handset and a keypad employing pushbutton display keys each of which has a writable keyface display for visually indicating the function of the key or other information to the user. The personal computer is connected to both the phone device and to one or more telephone communications channels and is programmed to display prompting information on the key displays and respond to keypress events to perform the functions indicated. The user can perform a variety of telephone system management tasks solely by viewing and manipulating the phone device keypad, including manual dialing, redialing, speed-dialing from a directory of commonly called numbers, making flash disconnections, forwaring calls, controlling call waiting and caller I.D. functions, adjusting speakerphone volume and microphone gain, handling conference calls, automatically logging into remote databases, recording the time and nature of each call in an accounting file, performing unattended call answering and voice mail functions, utilizing voice responsive and automated voice output systems, and other telephone management functions.

=> d ab 20

L6 ANSWER 20 OF 32 USPATFULL

AB A system and method for improving the performance of a processor that emulates a guest instruction where the guest instruction includes a first and second operand. The first operand is stored in a general purpose register, and the second operand is stored in a special-purpose register. The method and system provides a host instruction that performs an operation using the first operand and the second operand without moving the second operand from the special-purpose register into the general purpose register. This reduces the number of instructions in the semantic routines necessary to operate on immediate data from guest instructions and increases emulation performance.

=> d ab 21

L6 ANSWER 21 OF 32 USPATFULL

AB What is disclosed is an emulator that emulates on an execution machine the operation of a target machine. The emulator emulates routines that are called via a jump table such as the BIOS. Control is transferred to an emulation module not by directly trapping the procedure to call the BIOS but by placing a privileged instruction (a "halt instruction, for example) in the area called and by causing a trap through the execution of the privileged instruction. An identifier is placed after the halt instruction and a needed BIOS emulation module is called by a dispatcher

using this identifier. Therefore, normal operation can be obtained even if there is a resident program which rewrites the jump table.

=> d 21

L6 ANSWER 21 OF 32 USPATFULL

AN 1998:59535 USPATFULL

TI Computer emulator

IN Ogata, Hideaki, Nagano-Ken, Japan
Tanimoto, Akihito, Nagano-Ken, Japan
Nakaoka, Yasushi, Nagano-Ken, Japan
Kojima, Masanori, Nagano-Ken, Japan
Akahori, Yutaka, Nagano-Ken, Japan

PA Seiko Epson Corporation, Tokyo, Japan (non-U.S. corporation)

PI US 5758124 19980526

AI US 1995-559223 19951117 (8)

PRAI JP 1994-309813 19941118

DT Utility

LN.CNT 883

INCL INCLM: 395/500.000

INCLS: 395/527.000; 395/421.030; 364/DIG.001; 364/232.300; 364/DIG.002;
364/927.810; 364/955.500

NCL NCLM: 395/500.480

NCLS: 395/527.000; 711/213.000

IC [6]

ICM: G06F009-455

EXF 395/500; 395/375; 395/750; 395/800; 395/416; 395/527; 395/421.03;
364/200MSFile; 364/900MSFile; 364/927.81

=> d ab 22

L6 ANSWER 22 OF 32 USPATFULL

AB Application programs compiled for a first, "source", computer are translated, from their object form, for execution on a second, "target", computer. The translated application programs are linked or otherwise bound with a translation of the source computer system software. The translated system software operates on the

image of the source computer address space in the target computer exactly as it did in the source computer. The semantics of the source computer system software are thus preserved identically. In addition, a virtual hardware environment is provided in the target computer to manage events and to deal with differences in the address space layouts between the source and target computers.

=> d ab 23

L6 ANSWER 23 OF 32 USPATFULL

AB A method and system provides a special purpose or embedded system

developer with the ability to confirm the correct operation of a computer program designed to operate on a target system whose processing and storage capabilities may be more austere than the host system upon which the computer program is designed and tested. A key feature of the method and the system enables a developer to execute and debug an application program on a host system while observing and testing the operation of the program through the input/output of the target system. Another feature of the method and system is an application loader that dynamically sizes and, as necessary, reconfigures the available memory to permit multiple applications to reside simultaneously on the target system by resolving addresses in the target system at the time an application of interest is downloaded to the target system.

=> d 23

L6 ANSWER 23 OF 32 USPATFULL
AN 1998:12908 USPATFULL
TI Method and system for loading and confirming correct operation of an application program in a target system
IN Barnstijn, Michael A., Kitchener, Canada
Church, Mark E., Kitchener, Canada
Linkert, Barry W., Kitchener, Canada
Lazaridis, Mihal, Waterloo, Canada
PA Research In Motion Limited, Waterloo, Canada (non-U.S. corporation)
PI US 5715387 19980203
AI US 1996-742632 19961101 (8)
RLI Continuation of Ser. No. US 1995-386528, filed on 10 Feb 1995, now patented, Pat. No. US 5600790
DT Utility
LN.CNT 746
INCL INCLM: 395/183.140
INCLS: 395/183.180; 395/704.000
NCL NCLM: 714/038.000
NCLS: 395/704.000; 714/042.000
IC [6]
ICM: G06F009-455
EXF 395/183.14; 395/705; 395/183.18; 395/704; 395/427; 395/497.02

=> d ab 24

L6 ANSWER 24 OF 32 USPATFULL
AB A Target MCU is restored to a Target State. A Host Trace of Debug Commands is preserved as the Target MCU is driven from a known first state to the Target State by executing a series of Debug Commands. The Target MCU is then reinitialized to the known first state. The Debug Commands are read from the Host Trace and sent to a Modular Development System (MDS) for execution by the Target MCU until the Target MCU is again driven to the Target State.

=> d kwic 24

L6 ANSWER 24 OF 32 USPATFULL
SUMM . . . "real-time debugger" in that they cover half of the bases. A developer must not only be able to observe the execution of his application in real-time, but also be able to change parameters of his application, and be able to generate events

in real-time order to modify program flow-control. This functionality would give the developer a better feel for the execution of his application.

DETD The MCUdebug software system is an application development and debugging environment for embedded microcontrollers. It allows users to edit, build, and debug their applications all within the same graphical user interface. It dynamically supports a variety of execution targets, including in-circuit emulators, evaluation systems and boards, and instruction set simulators.

DETD . . . on a different platform (such as a personal computer or a workstation), and then downloaded into the MCU memory for execution and debugging. For example, one could develop his application for a Motorola MC68HC08.TM. microcontroller using tools available for either Microsoft Windows.TM. or UNIX.TM.. Using a debugger, the object code generated can then be downloaded into the target evaluation system for executing and debugging the application.

DETD Since embedded MCUs do not support basic input/output, a console window is not available where a developer can observe the execution of his application. Also, no interaction can take place between an application and its developer during program execution. Normally, a debugger can be used to provide something close to a console, since it allows a user to observe the state of his application at any point. Debuggers also allow a user to perform traditional debugging operations like instruction tracing and programmed breakpoints.

DETD . . . in embedded systems, since these capabilities allow a user the capability to track the exact flow of control through his application. These capabilities can be used without stopping program execution, and thus are particularly useful in real-time systems for which breakpointing would be inconvenient.

DETD . . . command line within the MCUdebug environment, a user has to perform the following: in the "Customize Assembler" dialog, the "Assembler Executable" box should be set to "casm05, and "Assembler Options" box should be set to the string "l s d". No further setup is required for this application (since it only requires an assembler). If the toolset contained a compiler, assembler, linker, and locator, a little more toolset. . .

DETD Execution control is essential to observe the flow of execution through a program. MCUdebug provides the user a wide variety of commands to support execution control. Commands such as "animate", "go", "gotil", "trace", and "step" are provided so a user can run his application, trace instructions, or execute his application until a specific section is reached.

DETD The MCU reset vector is used extensively in embedded applications to return an application to a known starting state in case of abnormal program execution. It can also be used by a user externally while debugging to return his application to a known starting state. The MCUdebug command "reset" loads the MCU program counter ("pc") with the contents of the . . . the "resetgo" command will load the MCU program counter ("pc") with the contents of the reset vector and begin program execution.

DETD For example, to run his application a user can use a "go" command. That starts execution of his application program, which runs until the user types a "stop" command. If the user wishes to execute his application until a certain address, he can use a "gotil" command (he must specify the ending address). If the user wishes to trace the execution of a single instruction, he can use a "t" command (an additional parameter <n> can be specified which allows them to trace <n> instructions). If

the user wishes to return to the starting point of the application, he can use a "reset" command.

DETDX Script, command, or log files allow a user to maintain a log of all the commands that he has **executed** during an MCUdebug session (command names "script" or "cf"). It also allows the user the capability

to perform regression tests on his target embedded **application**. These scripts are ASCII files, so a user can copy or edit these files for reuse, as necessary.

DETDX . . . to display a source window with a highlight line (the highlight line reflects the exact point in the source). Visual **execution** control allows a user a more abstract mechanism for controlling program **execution**. Instead of keeping track of explicit addresses in his **application**, he can control program **execution** using actual source code.

DETDX . . . EQU \$40

PA5. EQU \$20
PA4. EQU \$10
PA3. EQU \$08
PA2. EQU \$04
PA1. EQU \$02
PA0. EQU \$01
DDRA EQU \$04 . . . ;PORT A DATA DIRECTION REGISTER
DDRA7 EQU 7 . . . ;BIT #7 OF PORT A DDR
DDRA6 EQU 6
DDRA5 EQU 5
DDRA4 EQU 4
DDRA3 EQU 3
DDRA2 EQU 2
DDRA1 EQU 1

DDRA0. . . . OF DDRA7
DDRA6 EQU \$40
DDRA5. EQU \$20
DDRA4. EQU \$10
DDRA3. EQU \$08
DDRA2. EQU \$04
DDRA1. EQU \$02
DDRA0. EQU \$01

TCR EQU \$12 . . . ;TIMER CONTROL REGISTER
ICIE EQU 7 . . . ;INPUT CAPTURE INTERRUPT ENABLE BIT
OCIE EQU 6 . . . ;OUTPUT COMPARE INTERRUPT ENABLE BIT
TOIE ;TIMER OVERFLOW INTERRUPT ENABLE BIT

ICIE. EQU. ;BIT POSITION
OCIE. EQU \$40 . . . ;OUTPUT COMPARE INTERRUPT BIT POSITION
TOIE. EQU \$20 . . . ;TIMER OVERFLOW INTERRUPT BIT POSITION
TSR EQU \$13 . . . ;TIMER STATUS REGISTER

ICF EQU 7 . . . ;INPUT CAPTURE FLAG BIT
OCF EQU 6 . . . ;OUTPUT COMPARE FLAG BIT
TOF EQU 5 . . . ;TIMER OVERFLOW FLAG BIT

ICF. EQU \$80. ;INPUT CAPTURE FLAG BIT POSITION
OCF. EQU \$40 . . . ;OUTPUT COMPARE BIT POSITION
TOF. EQU \$20 . . . ;TIMER BIT POSITION

OCRH EQU \$16 . . . ;OUTPUT COMPARE REGISTER (HIGH BYTE)
OCRL EQU \$17 . . . ;OUTPUT COMPARE REG (LOW BYTE)
TCRH EQU \$18 . . . ;TIMER COUNTER REGISTER (HIGH BYTE)

TCRL EQU \$19 . . . ;TIMER COUNTER REG (LOW BYTE)

ACRH EQU \$1A . . . ;ALTERNATE COUNTER REG (HIGH BYTE)

ACRL EQU \$1B ;START OF ON-CHIP RAM

ROMStart EQU \$0100 . . . ;START OF ON-CHIP ROM

ROMEnd EQU \$08FF . . . ;END OF ON-CHIP ROM

Vectors

EQU \$1FF8 . . . ;RESET/INTERRUPT VECTOR AREA

Application specific equates

```

LED EQU PA7      LED ON WHEN PA7 IS LOW
LED. EQU PA7.    LED BIT POSITION
Put program variables here (Use RMBs)
. . . INTERRUPTS
STA TCR
BRCLR OCF,TSR,NEXT ;IF OCF IS NOT SET, SKIP INTERRUPT FLAG
RESET
LDA TSR      ;READ TIMER STATUS & OUTPUT COMPARE
REGISTER
LDA OCRL    ;TO CLEAR THE INTERRUPT
NEXT LDA #3     ;OCFs COUNT 3.fwdarw.0
STA OCFs    ;SET OUTPUT COMPARE INTERRUPT COUNT
TO 3
CLR. . . ;SET OCR SO THAT INTERRUPT IS GENERATED
;ON THE NEXT OCCURENCE OF THE COUNT VALUE
;COPIED FROM THE TIMER COUNTER REGISTER.
;THIS COUNT WILL OCCUR AFTER ONE COMPLETE
;CYCLE OF THE COUNTER, THAT IS 262,144 CYCLES
;FOR A TOTAL OF 131.072ms. . . INT
;OPERATING FREQUENCY)
CLI ;CLEAR I BIT IN STATUS REG TO ENABLE INTERRUPT
MAIN -- Beginning of main program loop. Loop is
executed once every 400ms (393.216ms). A pass through
all major task routinestakes less than 400ms and then
time is wasted until MSB of. . . interrupt, the
interrupt is serviced (OCFs gets decremented (3.fwdarw.0)
and then cleared by reading the TSR and low byte of
the Output Compare Register (OCRL). When OCFs=0, MSB
of TIC gets set and OCFs is set back to 3.
(3*131.072ms/OCF = 393.216ms)
The variable TIC keeps track. . .

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=> d kwic 25

L6 ANSWER 25 OF 32 USPATFULL

SUMM In addition to testing for functionality and for manufacturing defects, application software development requires a similar level of simulation, observability and controllability in the system or sub-system design phase. The emulation phase of design should ensure that an IC (integrated circuit), or set of ICs, functions correctly in the end equipment. . .

SUMM . . . simulation and continually increasing cost of CAD (computer aided design) tools. In the board design the side effects include decreased register visibility and control, complicated debug and simulation in design verification, loss of conventional emulation due to loss of physical access by packaging many circuits in one package, increased routing complexity on the board, increased costs of design tools, mixed-mode packaging, and design for producability. In application development, some side effects are decreased visibility of states, high speed emulation difficulties, scaled time simulation, increased debugging complexity, and increased costs of emulators.

Production side effects involve decreased visibility and control, complications in test vectors and models, increased test complexity, mixed-mode packaging, continually. . .

SUMM Among the objects of the present invention are to provide improved emulation, simulation and testability architectures and methods which provide visibility and control without physical probing or special test fixtures; to provide improved emulation, simulation and testability architectures and methods which are applicable to critical components of system designs to support test and integration of both hardware and software; to provide improved emulation,

simulation and testability architectures and methods that are a viable alternative to high capital-cost test equipment and systems; to provide improved emulation, simulation and testability architectures and methods which integrate access to sophisticated operations in hardware emulation, fault emulation, simulation and built-in test; to provide improved emulation, simulation and testability architectures and methods which apply hardware and software visibility and control to reduce application

development time and thus reduce the user manufacturer's time-to-market on new products; and to provide improved emulation, simulation and testability architectures and methods to leverage hierarchical partitioning and automatically generate reusable tests for related chips and systems.

SUMM . . . one form of the invention is an electronic system including electronic circuitry to be tested and including serial scan shift register latches, and a serial scan generator embedded in the system in manufacture and connected to the electronic circuitry thereby facilitating. . .

DETD . . . 347,967 (TI-14145), and Ser. No. 347,969 (TI-14147). For example, device 11 has sets of serially connected set of serial shift register latches (SRLS) distributed through the device like beads on a string for input and output of emulation signals serially. The. . .

DETD . . . additions is simply connected by a parallel cable 304 to terminals 1189 to parallel bus 1187 to SBM-2 on the application system 1181 in the field, or even in manufacture. A test program is inserted in host computer 300 and executed.

DETD In read synchronization, circuitry in SBM 101 supports an Update command

that loads all status register***

<-----User Break----->

u

=>

=> d ab 25

L6 ANSWER 25 OF 32 USPATFULL

AB An electronic system for use with a host computer. The system includes electronic circuitry including a first semiconductor chip generally operable for a first function and also adapted for input and output of emulation signals. This is combined with emulation circuitry including

a second semiconductor chip adapted for connection to the host computer. The emulation circuitry is connected to the electronic circuitry to generate emulation signals to input to the electronic circuitry and to accept emulation signals from the electronic circuitry. A physical assembly supports the emulation circuitry and the electronic circuitry as a unit. Other electronic systems and emulation and testing devices, cables, systems and methods are also disclosed.

=> d 25

L6 ANSWER 25 OF 32 USPATFULL

AN 97:102464 USPATFULL

TI Electronic systems and emulation and testing devices, cables, systems and methods

IN Swoboda, Gary L., Sugar Land, TX, United States

Hoar, Henry R., Houston, TX, United States

Coomes, Joseph A., Missouri City, TX, United States

PA Texas Instruments Incorporated, Dallas, TX, United States (U.S. corporation)

PI US 5684721 19971104

AI US 1992-851232 19920313 (7)

RLI Continuation [REDACTED] Ser. No. US 1989-401198, filed [REDACTED] 28 Aug 1989, now abandoned which is a continuation-in-part of Ser. No. US 1986-948337, filed on 3 Dec 1986, now abandoned which is a continuation-in-part of Ser. No. US 1987-93463, filed on 4 Sep 1987, now abandoned

DT Utility

LN.CNT 2012

INCL INCLM: 364/578.000
INCLS: 364/488.000; 364/489.000; 395/500.000

NCL NCLM: 395/500.440

IC [6]
ICM: G06F017-00
ICS: G06G007-06

EXF 364/578; 364/488; 364/489; 371/23; 371/22.2; 371/22.3; 395/500

=> d ab 26

L6 ANSWER 26 OF 32 USPATFULL

AB An emulation device (11) distributes common control information (8801) to each of a plurality of clock domains (1213, 1215, 1217) into which the emulation device is partitioned, and also provides the clock domains with individualized clock control (8905, 8907, 8913).

=> d ab 27

L6 ANSWER 27 OF 32 USPATFULL

AB A method and system provides a special purpose or embedded system developer with the ability to confirm the correct operation of a computer program designed to operate on a target system whose processing and storage capabilities may be more austere than the host system upon which the computer program is designed and tested. A key feature of the method and the system enables a developer to execute and debug an application program on a host system while observing and testing the operation of the program through the input/output of the target system. Another feature of the method and system is an application loader that dynamically sizes and, as necessary, reconfigures the available memory to permit multiple applications to reside simultaneously on the target system by resolving addresses in the target system at the time an application of interest is downloaded to the target system.

=> d 27

L6 ANSWER 27 OF 32 USPATFULL

AN 97:10989 USPATFULL

TI Method and system for loading and confirming correct operation of an application program in a target system

IN Barnstijn, Michael A., Kitchener, Canada
Church, Mark E., Kitchener, Canada
Linkert, Barry W., Kitchener, Canada
Lazaridis, Mihal, Waterloo, Canada

PA Research In Motion Limited, Waterloo, Canada (non-U.S. corporation)

PI US 5600790 19970204

AI US 1995-386528 19950210 (8)

DT Utility

LN.CNT 798

INCL INCLM: 395/183.140

NCL INCLS: 395/500.000; 395/200.010
NCLM: 714/035.000
NCLS: 395/500.440
IC [6]
ICM: G06F009-455
EXF 395/183.14; 395/183.13; 395/183.01; 395/700; 395/650

=> d ab 28

L6 ANSWER 28 OF 32 USPATFULL

AB An integrated circuit terminal of a data processing system (10) is used to communicate multiplexed signals with an external device. During a reset operation in which a reset signal is asserted, a desired internal clock signal is driven to the integrated circuit terminal such that an emulation system (52) may use the internal clock signal to synchronize an emulation operation. After the reset signal is negated, the emulation system synthesizes the internal clock signal for use during emulation. External visibility of a write operation to a register which controls pertinent signal parameters is provided via other integrated circuit terminals when the data processor operates in an emulation mode. The external visibility allows the development system to make similar changes to corresponding signal parameters therein. Therefore, the development system is able to accurately synchronize an emulation operation even when signal parameters are modified during operation.

=> d ab 29

L6 ANSWER 29 OF 32 USPATFULL

AB Operations of a data processing device are traced by detecting a jump address in the program counter sequence, and pushing the jump address onto a trace stack.

=> d ab 30

L6 ANSWER 30 OF 32 USPATFULL

AB An emulation device including a serial scan testability interface having at least first and second scan paths, and state machine circuitry connected and responsive to said second scan path generally operable for emulation control of logical circuitry associated with said emulation device.

=> d kwic 30

L6 ANSWER 30 OF 32 USPATFULL

SUMM In addition to testing for functionality and for manufacturing defects, application software development requires a similar level of simulation, observability and controllability in the system or sub-system design phase. The emulation phase of design should ensure that an IC (integrated circuit), or set of ICs, functions correctly in the end equipment. . .
SUMM . . . simulation and continually increasing cost of CAD (computer aided design) tools. In the board design the side effects include decreased register visibility and control, complicated debug

and simulation in design verification, loss of conventional **emulation** due to loss of physical access by packaging many circuits in one package, increased routing complexity on the board, increased costs of design tools, mixed-mode packaging, and design for producability. In **application development**, some side effects are decreased visibility of states, high speed **emulation** difficulties, scaled time simulation, increased debugging complexity, and increased costs of **emulators**.

Production side effects involve decreased visibility and control, complications in test vectors and models, increased test complexity, mixed-mode packaging, continually.

SUMM Among the objects of the present invention are to provide improved **emulation**, simulation and testability architectures and methods which provide visibility and control without physical probing or special

test fixtures; to provide improved **emulation**, simulation and testability architectures and methods which are applicable to critical components of system designs to support test and integration of both hardware and software; to provide improved **emulation**, simulation and testability architectures and methods that are a viable alternative to high capital-cost test equipment and systems; to provide improved **emulation**, simulation and testability architectures and methods which integrate access to sophisticated operations in hardware **emulation**, fault **emulation**, simulation and built-in tests to provide improved **emulation**, simulation and testability architectures and methods which apply hardware and software visibility and control to reduce **application development** time and thus reduce the user manufacturer's time-to-market on new products; and to provide improved **emulation**, simulation and testability architectures and methods to leverage hierarchical partitioning and automatically generate reusable tests for related chips and systems.

DRWD FIG. 59A is a compact diagram of shift **register latches** SRLs in a scan chain in FIG. 59;

DRWD FIG. 83 is a schematic of a parallel **register latch** for use in the GSP chip of FIG. 80;

DRWD FIG. 84 is a schematic of a serial **register latch** for use in the GSP chip of FIG. 80;

DETD Extended development system 1101 provides full-speed, in-circuit **emulation** for system design and for hardware and software debug on widely available personal computer systems. The development tools provide technological . . . to prototype. The development system elements provide ease of use and offer the designer the tools needed to significantly reduce **application system development** time and cost to put designs into production faster.

DETD . . . configuration file, a GSP (graphic signal processor) configuration, a programmable array logic (PAL) file, an ASIC file and a

GPL **register file**.

DETD . . . software and hardware with the target system. An important emulation interface provides control and access to every memory location

and **register** of the target chip and extend the device architecture as an attached processor.

DETD . . . before the target system is complete. To accomplish this, code is downloaded into the memory on the board 1043 and **executed** at full speed via the interface on an **application board** used in place of the incomplete target system. A suitable **application board** includes a DSP 11, 16K.times.32 bits of full-speed (zero wait states) SRAM on a primary bus, two selectable banks. . .

DETD . . . in coassigned application Ser. No. 057,078 issued Aug. 22, 1989, (U.S. Pat. No. 4,860,290) and incorporated herein by reference. Shift **register latches** (SRLs) designated "S" are distributed through the device 11 like a string of beads on a serial scan path. .

DETD . . . TDO communicate with the system. TMS and TCK communicate with a tap controller 1151 which is connected to an instruction register 1153 and an instruction decoding circuit 1155.

DETD Test access port (TAP) controller 1151 is in turn coupled to instruction register (IR) 1153 and a first multiplexer 1173. The instruction register can receive serial scan signals from the TDI line and output serially to MUX 1173. MUX 1173 is under control of the TAP and can select the output signal from the instruction register or from another MUX 1171.

DETD The instruction register also controls a bypass register (BR) 1167 and one or more boundary scan registers (BSR) 1161. The bypass register receives the TDI signal and outputs it to MUX 1171. MUX 1171 is under control of the instruction register 1153. Based on the instruction loaded into the instruction register, MUX 1171 outputs its input from the bypass register or its input from one or more BSRs, or internal device register scan. Each boundary scan register is controlled via the test access port and the instruction register.

DETD . . . or a test mode. During the normal mode, input data entering terminals of IC logic passes through the boundary scan register , into the IC logic and out to the normal output terminals without any change due to the BSR. During the . . . test mode, normal input data is interrupted, and test input data is captured, shifted, and updated within the boundary scan register. The boundary scan register includes two memories, a first memory for receiving and shifting data from the TDI line and a second memory for. . .

DETD . . . controller card 1141 through pin TDI and enters any one of a number of shift registers, including a boundary scan register 1161, a device identification register 1163 and design specific test data registers 1165. A bypass register 1167 is also provided. These shift registers or serial scan registers are selected via a MUX 1171 under the control. . . output from MUX 1171 is fed to a MUX 1173 so that under control of tap controller 1151 the instruction register 1153 or MUX 1171 is selected by MUX 1173.

DETD JTAG clock TCK and MUX 1173 output are fed to flip. . .

DETD . . . has two scan paths. One of the scan paths is termed the MPSD data path which usually has numerous shift register latches S (or SRL) serially interconnected like a string of beads throughout the module. The second scan path is termed the MPSD control path which generally has fewer shift register latches and which selects which MPSD data paths are to be scanned. These scan paths are described in above-cited application. . .

DETD . . . core domain 1213, system domain 1215 and analysis domain 1217 are shown in FIG. 50 and interface through the shift register latches of FIG. 47 to all of the various parts of the chip.

DETD . . . chip of device 11. JTAG control 1201 interfaces with the pins via a serial boundary scan assembly including boundary scan register 1161 which allows all logic states at the actual pins of device 11 to be read or written. JTAG TAP controller 1151 and JTAG instruction register IR 1153 are provided on-chip. Test control 1205 and MPSD control 1203 are integrated into the circuitry. MPSD control 1203. . .

DETD . . . as the following five distinct clocking domains in order to control domain data transfers with the scan clock (JCLK) and application execution with the functional clock (FCLK).

DETD . . . data is scanned to and from the device 11 through internal paths that are selected through a JTAG instruction register 1153. A unique JTAG opcode for each path allows entry of and access to internal scan data.

DETD FIG. 54 shows a further diagrammatic perspective of the registers of

FIG. 50 where JTAG instruction register IR 1153 is selected for scan between the terminals TDI and TDO. The IR 1153 is decoded in FIG. 50. . . requested by the control card 1141 of FIG. 45 via the serial line 1103. These shift registers are the bypass register 1167, the boundary scan register 1161, the message peripheral 1216 of FIG. 52, the emulation control register 1251 and a pair of MPSD scan paths 1252 in the various domains and modules in the domains.

- DETD . . . when not scanning and a zero when scanning. CO and CX are sourced from the emulation control block adapter 1203 register 1251. When host computer 1101 detects Ready to Scan for all unlocked domains for a designated device on the target. . .
- DETD . . . mode conditioned stop logic circuitry 13098, 1309C and 1309A in the domains respectively. The modes are established by a mode register 1311 which is scanable in FIGS. 54 and 57 to establish the type of stop and any other desired mode. . .
- DETD . . . sent to the CPU domain 1213 to make it stop according to the stop mode established for it in mode register 1311 and mode conditioned stop circuitry 1309C. DONE circuitry 1363 detects when the stop is completed and signals back to. . .
- DETD . . . an example of process steps by which the scan control 1149 including IR 1153, adapter 1203 including ECR (emulation control register) 1251, and host computer 1101 cooperate to enter and perform sequences of commands on-chip.
- DETD . . . to reach the state "Select-DR-Scan". This means that the scan controller is ready to accept scan into a DR (data register) identified just before as the ECR 1251 by the host to the IR 1153. Into ECR 1251 the host 1101. . .
- DETD In FIG. 59, serial scan bits enter the emulation control register ECR 1251 which is subdivided into a shift register LOCK 1351 for holding bits to lock and unlock domains, a first CO,CX control code shift register named CODA 1353, a second CO,CX control code shift register named CODB 1357, a shift register 1359 associated with event manager circuitry 1365, and a two-bit register JMODE 1360. These registers are compactly illustrated in FIG. 59A. Thus, the serial scan enters on a scan line SIN. . .
- DETD A code state machine 1381 controls a two input MUX 1383. MUX 1383 selects the CO,CX two-bit contents of shift register 1353 or 1357 and loads them into an enabled one of three flip flops 1393, 1395 and 1397. A lock control circuit 1401 operating under the control of lock shift register 1351 and code state machine 1381 sends lock signals to disable or enable each of the flip flops 1393, 1395. . .
- DETD . . . the test codes on line 1421, thus overriding the code state machine feature. This option is selected by scanning JMODE register with "00" (both bits zero). Thus, the preferred embodiment is accommodates direct host control of the domains, wherein the latter. . .
- DETD 2) Program state machine 1381 operations via REV (Register Event) register 1359 to respond to stimuli including:
- DETD . . . to JCLK (with a code 00 in both registers 1353 and 1357) and vice versa for each domain, via LOCK register 1351; and
- DETD The operation of code state machine 1381 is now further described. When the JTAG IR (Instruction Register 1153) is loaded with a scan path select command for path 1251, a line ECRSEL feeds a signal to state. . . whereupon the state machine 1381 enters a lock state.
- This allows the registers 1351, 1353 and 1357, the event manager register 1359, and JMODE register 1360 to be changed without disturbing the MPSD codes and clocks supplied from flip flops 1393, 1395, 1397 and selection circuits 1
- <-----User Break----->
- u

=>
=> d 30

L6 ANSWER 30 OF 32 USPATFULL
AN 94:60720 USPATFULL
TI Emulation devices, systems and methods utilizing state machines
IN Swoboda, Gary L., Sugar Land, TX, United States
Daniels, Martin D., Houston, TX, United States
Coomes, Joseph A., Missouri City, TX, United States
PA Texas Instruments Incorporated, Dallas, TX, United States (U.S.
corporation)
PI US 5329471 19940712
AI US 1993-84787 19930629 (8)
RLI Continuation of Ser. No. US 1992-911250, filed on 7 Jul 1992, now
abandoned which is a continuation of Ser. No. US 1989-387549, filed on
31 Jul 1989, now abandoned which is a continuation-in-part of Ser. No.
US 1987-93463, filed on 4 Sep 1987, now abandoned And a
continuation-in-part of Ser. No. US 1987-57078, filed on 2 Jun 1987,
now patented, Pat. No. US 4860290, issued on 2 Jun 1987
DT Utility
LN.CNT 4145
INCL INCLM: 364/578.000
INCLS: 364/DIG.001; 364/264.300; 364/264.500; 364/267.400; 364/267.700;
371/016.200; 395/500.000
NCL NCLM: 395/500.440
NCLS: 395/500.050; 395/500.340; 714/028.000; 714/030.000; 714/727.000
IC [5]
ICM: G06F015-20
EXF 364/578; 364/579; 364/580; 371/16.1; 371/16.2; 371/22.3; 395/500

=> d ab 31

L6 ANSWER 31 OF 32 USPATFULL
AB The present invention concerns an integrated circuit (1) comprising a
standard cell (4), an application cell (2) and a test cell (3)
designed in particular to store or to modify from outside the
integrated circuit the value of communication signals passing between the standard
cell and the application cell. The standard cell
executing instructions provided on an instruction bus (3B4) by a
program memory located in the application cell in response to
an instruction address carried by an instruction address bus (3A4), the
conductors of these buses constituting communication links. The
integrated circuit further includes a branching circuit for replacing
at least one erroneous instruction from the program memory with a
replacement instruction previously stored in the integrated circuit in
response to a predetermined state of the communication links.

=> d 31

L6 ANSWER 31 OF 32 USPATFULL
AN 94:38538 USPATFULL
TI Integrated circuit including a test cell for efficiently testing the
accuracy of communication signals between a standard cell and an
application cell
IN Dartois, Luc, Colombes, France
Dulongpont, Jacques, Pontoise, France
Reusens, Peter, Laarne, Belgium

PA Alcatel Radio phone, Paris, France (non-U.S. corporation)
PI US 5309444 1 503
AI US 1991-739544 19910802 (7)
PRAI FR 1990-9978 19900803
DT Utility
LN.CNT 949
INCL INCLM: 371/010.200
NCL NCLM: 714/710.000
IC [5]
ICM: G06F011-00
EXF 371/10.2; 371/10.1; 371/8.1; 371/24; 371/21.2; 365/200; 324/73.1;
324/158R

=> d ab 32

L6 ANSWER 32 OF 32 USPATFULL

AB For use in an information processing system 10, the system including a system bus 16 having a system address bus 16a and a system data bus 16b and at least two data processors 12 and 14 coupled to the system bus, emulation apparatus for enabling a first one of the data processors to execute, in conjunction with a second one of the data processors, a program requiring access to predetermined address locations associated with a specific type of device, typically an I/O device. The specific type of device is either not resident within the system or is resident at different address locations. The emulation apparatus includes circuitry 30 for detecting an occurrence of an access cycle by the first data processor to the predetermined address location, circuitry 50 for halting the first data processor before completion of the access cycle and circuitry 50 for notifying the second data processor that the first data processor is halted. The emulation apparatus further includes circuitry 24a for indicating to the second data processor a value of the predetermined address location being accessed and a type of access to the predetermined address location. The second data processor includes circuitry for interpreting the address value and type of access, for accessing a corresponding address location having a same type of specific device or a corresponding type of device and for causing the first data processor to be released to complete the access cycle.

=> d 32

L6 ANSWER 32 OF 32 USPATFULL
AN 92:17564 USPATFULL
TI Information processing system emulation apparatus and method
IN Morss, Stephen, Somerville, MA, United States
Dreyfus, Boris, Lexington, MA, United States
PA Wang Laboratories, Inc., Lowell, MA, United States (U.S. corporation)
PI US 5093776 19920303
AI US 1989-367297 19890615 (7)
DT Utility
LN.CNT 738
INCL INCLM: 395/500.000
INCLS: 364/232.300; 364/927.810; 364/DIG.001
NCL NCLM: 395/500.460
NCLS: 395/500.450
IC [5]
ICM: G06F009-00
EXF 364/927.81; 364/578; 364/232.3

=>
Connection closed by remote host

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Terms	Documents
L7 and ((emulat\$ adj4 object) same (operating adj system))	0

Database:

Search:

Search History**DATE: Tuesday, May 20, 2003** [Printable Copy](#) [Create Case](#)

Set Name Query
side by side

DB=USPT; PLUR=YES; OP=OR

		<u>Hit Count</u>	<u>Set Name</u>
			result set
<u>L11</u>	L7 and ((emulat\$ adj4 object) same (operating adj system))	0	<u>L11</u>
<u>L10</u>	L7 and (emulat\$ adj4 object)	2	<u>L10</u>
<u>L9</u>	L7 and (emulat\$ same object)	54	<u>L9</u>
<u>L8</u>	l7 and (emulation adj object)	0	<u>L8</u>
<u>L7</u>	((703/24)!.CCLS. (705/7 705/16 705/21 705/23 705/1)!.CCLS. (714/38)!.CCLS. (or/)!.CCLS.)	2177	<u>L7</u>
<u>L6</u>	L3 and (emulation adj object)	0	<u>L6</u>
<u>L5</u>	L3 and ((operating adj system) same (direct\$ or connect\$ or link\$ or interfac\$))	2	<u>L5</u>
<u>L4</u>	L3 and (operating adj system)	2	<u>L4</u>
<u>L3</u>	(5088033 or 5812668)[pn]	2	<u>L3</u>
<u>L2</u>	L1 and ratio	1	<u>L2</u>
<u>L1</u>	(6092048 or 5907490 or 5765140 or 5301320)[pn]	4	<u>L1</u>

END OF SEARCH HISTORY